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- Trigger and Data Acquisition requirements for LHC
- Example: Data flow in ATLAS (transport of event information from collision to mass storage)

# What are the challenges at LHC for DAQ?

## Challenge 1

- Physics – Rejection power
- Requirements for TDAQ driven by rejection power required for the search of rare events

## Challenge 2

- Accelerator – Bunch crossing frequency
- Highest energy and luminosity needed for the production of rare events in wide mass range

## Challenge 3

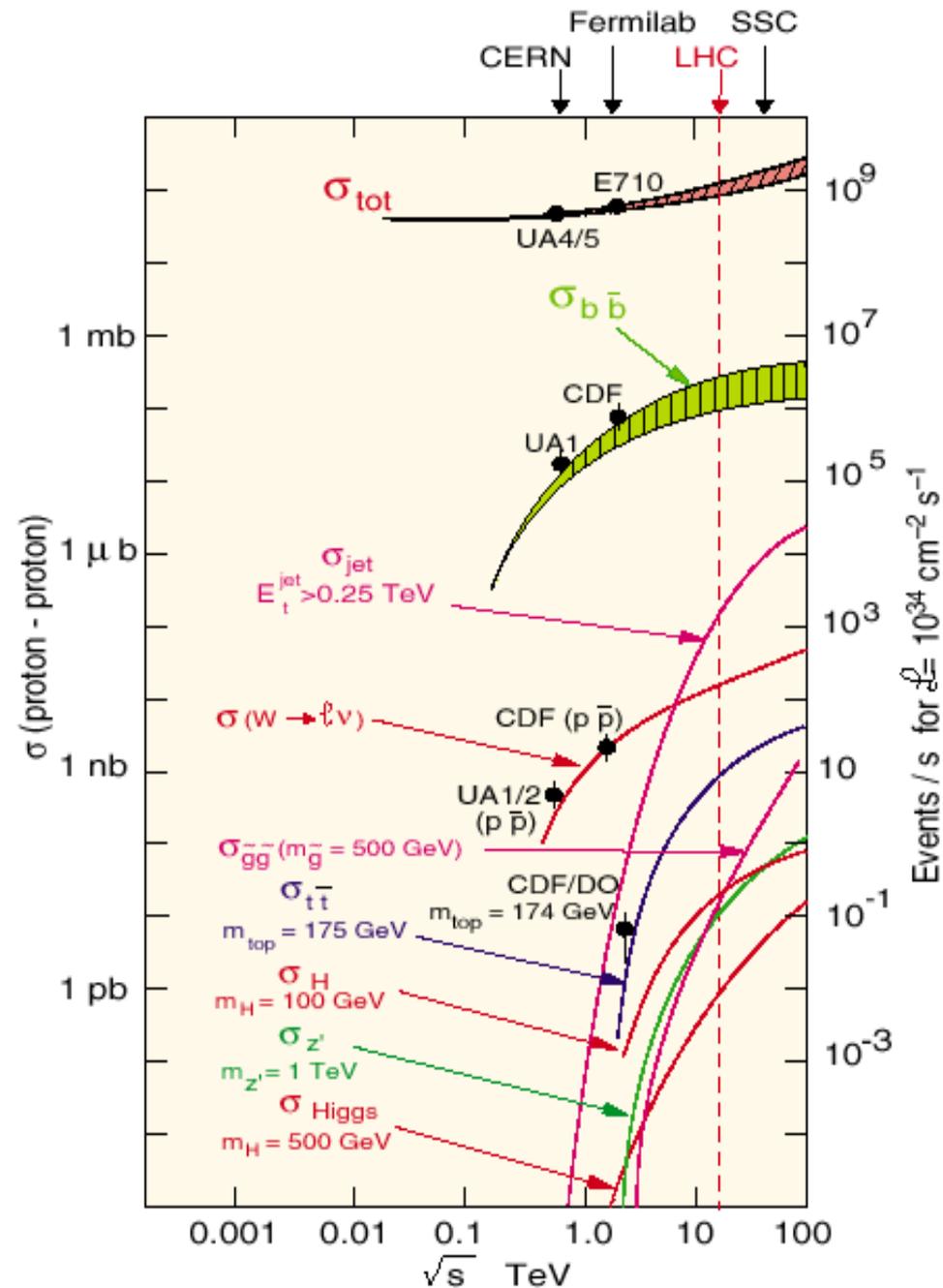
- Detector – Size and data volume
  - Unprecedented data volumes from a huge and complex detectors



# Challenge 1: Physics

- Cross sections for most processes at the LHC span  $\sim 10$  orders of magnitude
- LHC is a factory for almost everything:  $t$ ,  $b$ ,  $W$ ,  $Z$ ...
- But: some important signatures have small branching ratios (e.g.  $H \rightarrow \gamma\gamma$ , BR  $\sim 10^{-3}$ )

Process	Production Rate $10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
inelastic	$\sim 1 \text{ GHz}$
$b\bar{b}$	$5 \text{ MHz}$
$W \rightarrow l\nu$	$150 \text{ Hz}$
$Z \rightarrow l\nu$	$15 \text{ Hz}$
$t\bar{t}$	$10 \text{ Hz}$
$Z'$	$0.5 \text{ Hz}$
$H(120) \text{ SM}$	$0.4 \text{ Hz}$



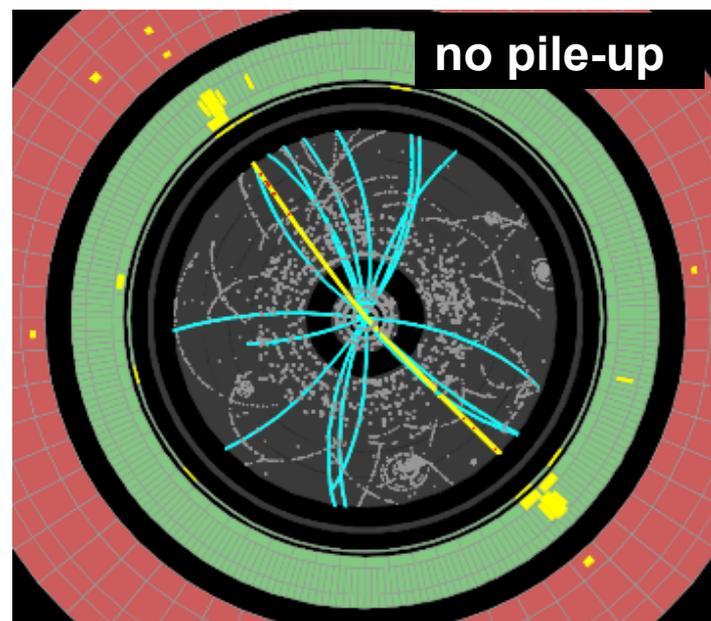
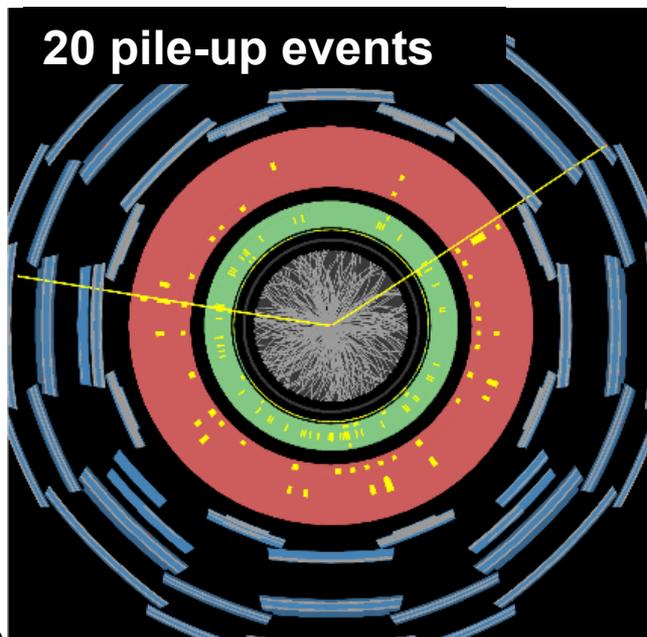
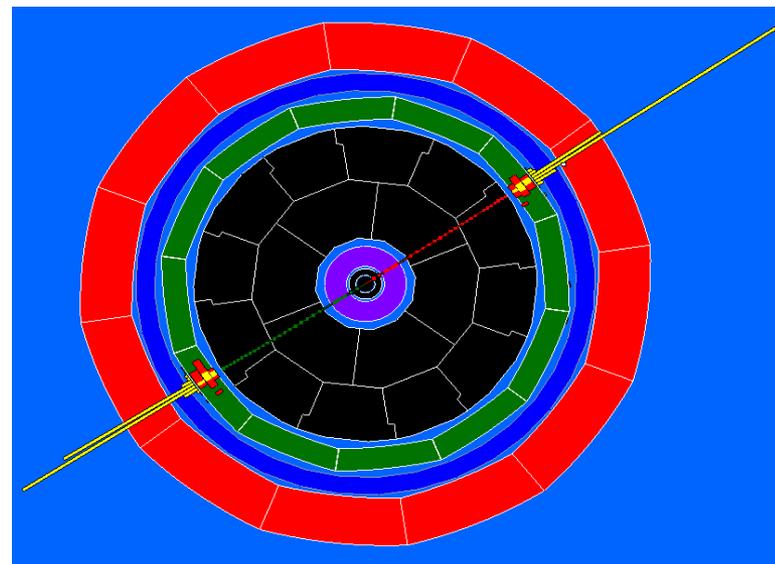
# Challenge 1: Physics

- Requirements for TDAQ driven by the search for rare events within the overwhelming amount of “uninteresting” collisions
- Besides the Higgs searches one of the motivations for the LHC are new particles outside the SM
  - Susy, extra-dimensions, new gauge bosons, compositeness, black holes etc.
- Be prepared for the ‘new unknown’, thus ensure you don’t reject what is out there by your trigger
- Selection criteria need to be flexible and scalable
  - Large luminosity range over lifetime of the experiments
  - ”Tunable” for new physics seen
- All of this must fit in around 300-1000 Hz of data writing to mass storage for physics analyses



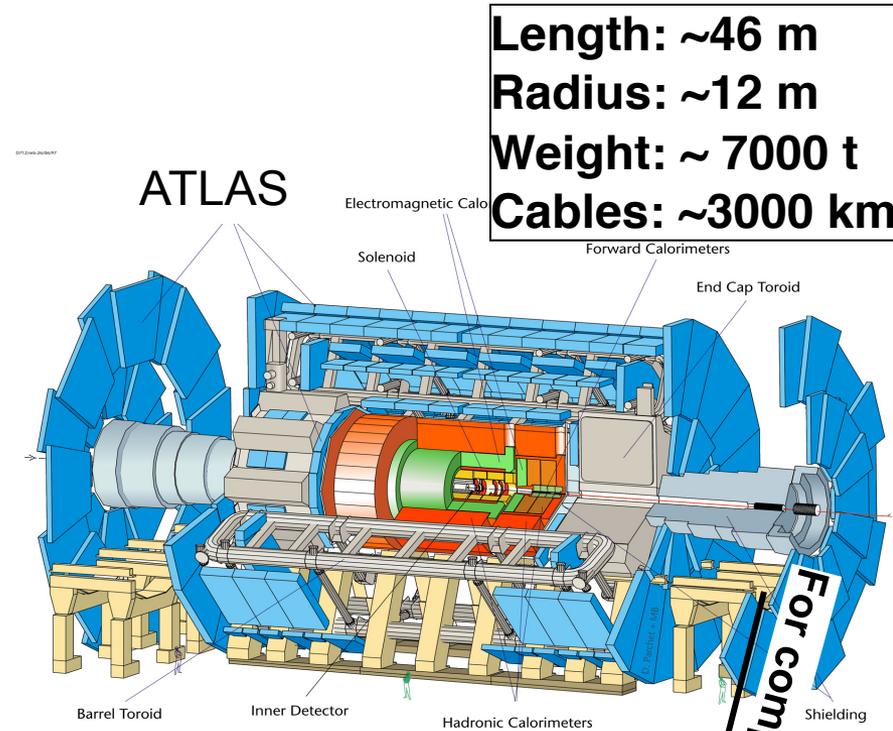
## Challenge 2: Accelerator

- Unlike  $e^+e^-$  colliders, proton colliders are more 'messy' due to proton remnants
- Bunch crossing frequency now is 20 MHz, will be 40 MHz at design lumi.
- LHC already produces now up to 30 overlapping p-p interactions on top of each collision (pile-up)  $\rightarrow$  >1000 particles seen in the detector!



# Challenge 3: Detector

- Besides being huge: number of channels are  $O(10^8)$  in ATLAS,  $O(10^7)$  in CMS, event size  $\sim 1.5$  mB
  - need huge number of connections
- Some detectors need  $> 25$ ns to readout their channels and integrate more than one bunch crossing's worth of information (e.g. LArg readout takes  $\sim 400$ ns)
  - need to identify bunch crossing...
- It's On-Line (cannot go back and recover events)
  - need to monitor selection - need very good control over all conditions



Length:  $\sim 46$  m  
Radius:  $\sim 12$  m  
Weight:  $\sim 7000$  t  
Cables:  $\sim 3000$  km



# Let's build a Trigger and DAQ for this

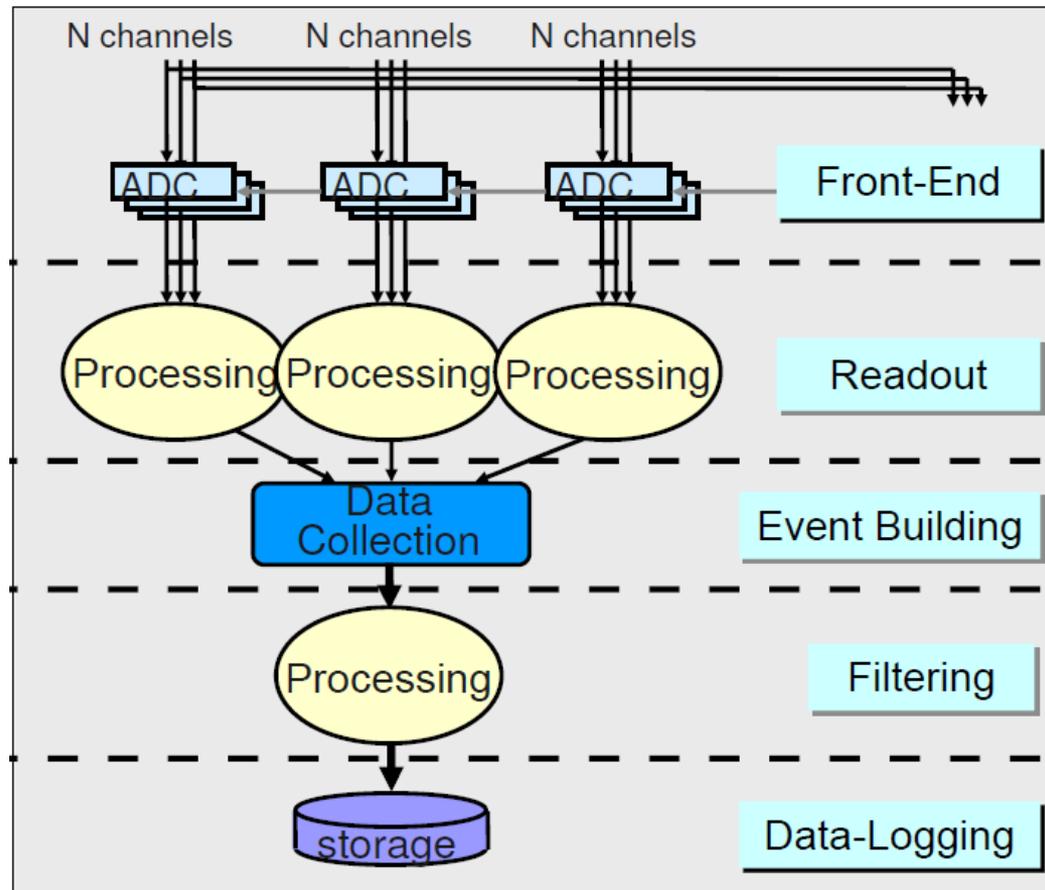
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- What do we need?

# Let's build a Trigger and DAQ for this

## What do we need?

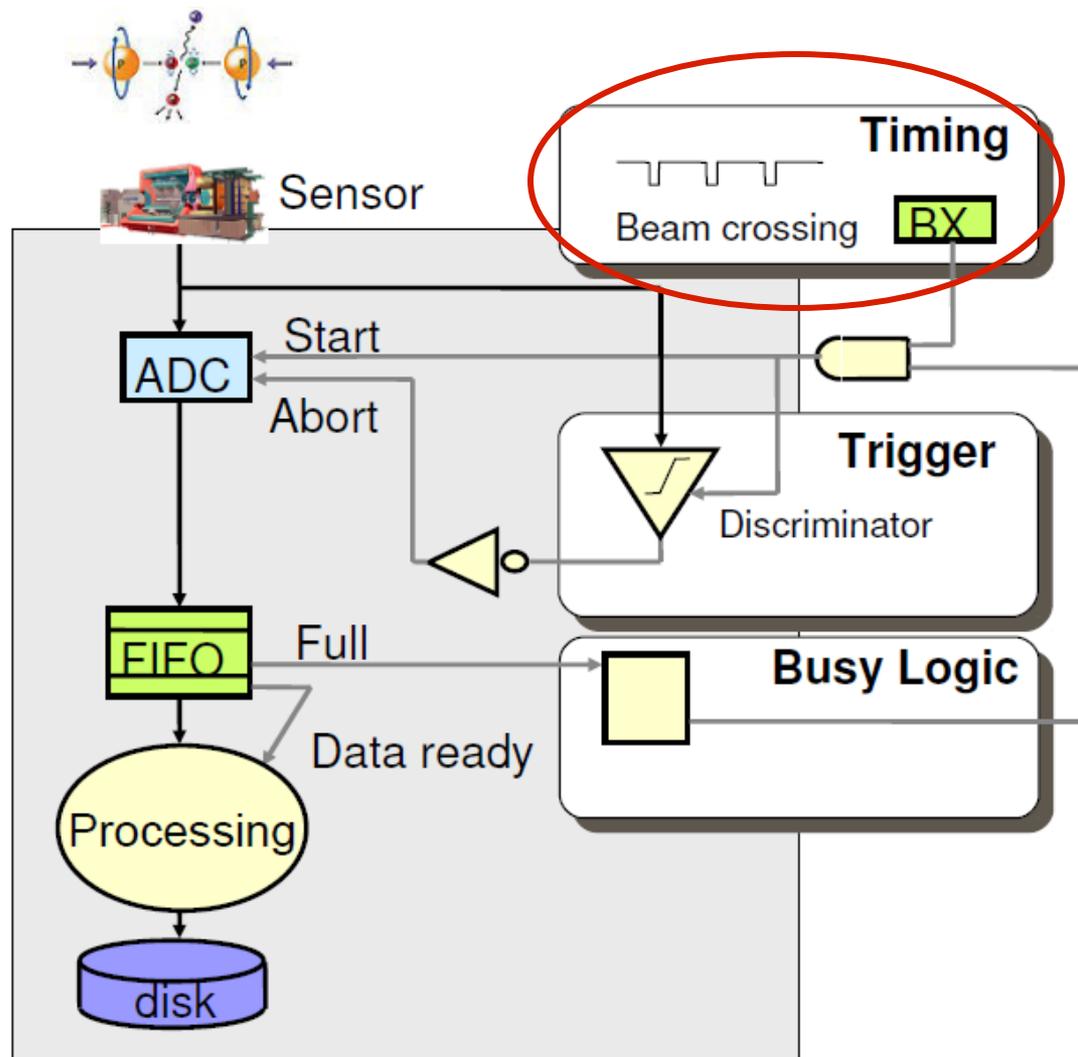
- Electronic readout of the sensors of the detectors (“front-end electronics”)
- A system to collect the selected data (“DAQ”)



# Let's build a Trigger and DAQ for this

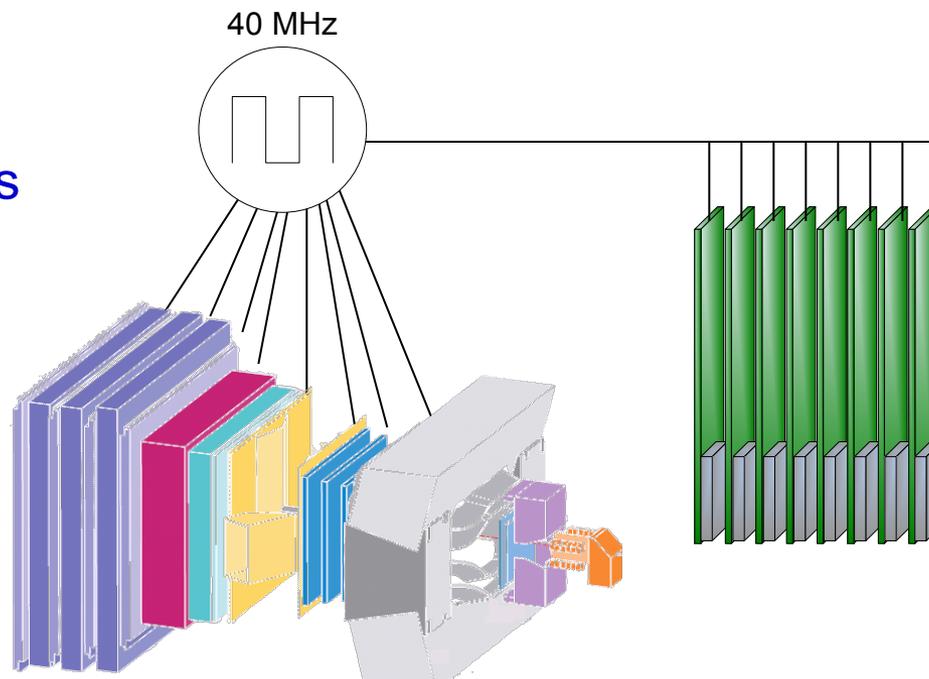
## What do we need?

- Electronic readout of the sensors of the detectors (“front-end electronics”)
- A system to collect the selected data (“DAQ”)
- A system to keep all those things in sync (“clock”)



# Timing

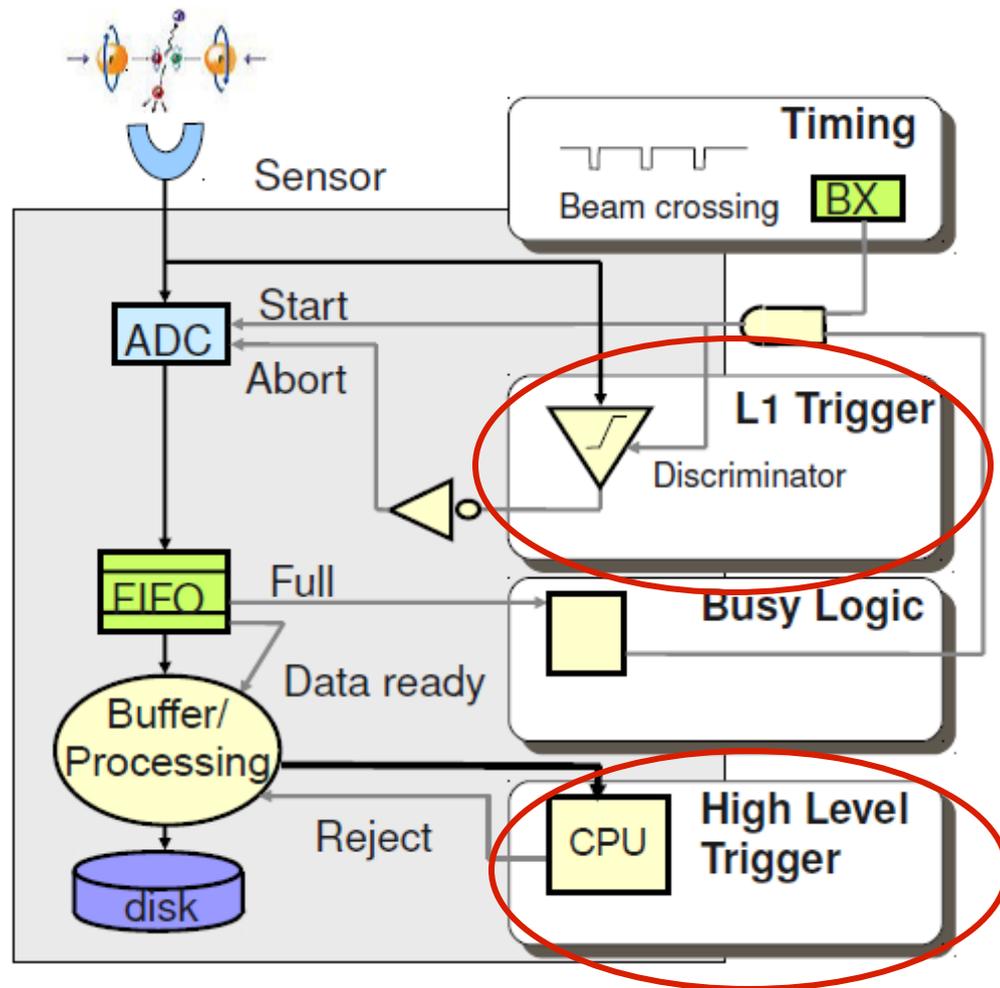
- An **event** is a snapshot of the values of all detector front-end readout units caused by the same collision
- A common clock signal must be provided to all detector elements
  - Since clock is a constant, detectors large and electronics fast, the **detector elements must be carefully time-aligned**
- Common system for all LHC experiments: **TTC** (Trigger, Timing and Control) based on radiation-hard opto-electronics



# Let's build a Trigger and DAQ for this

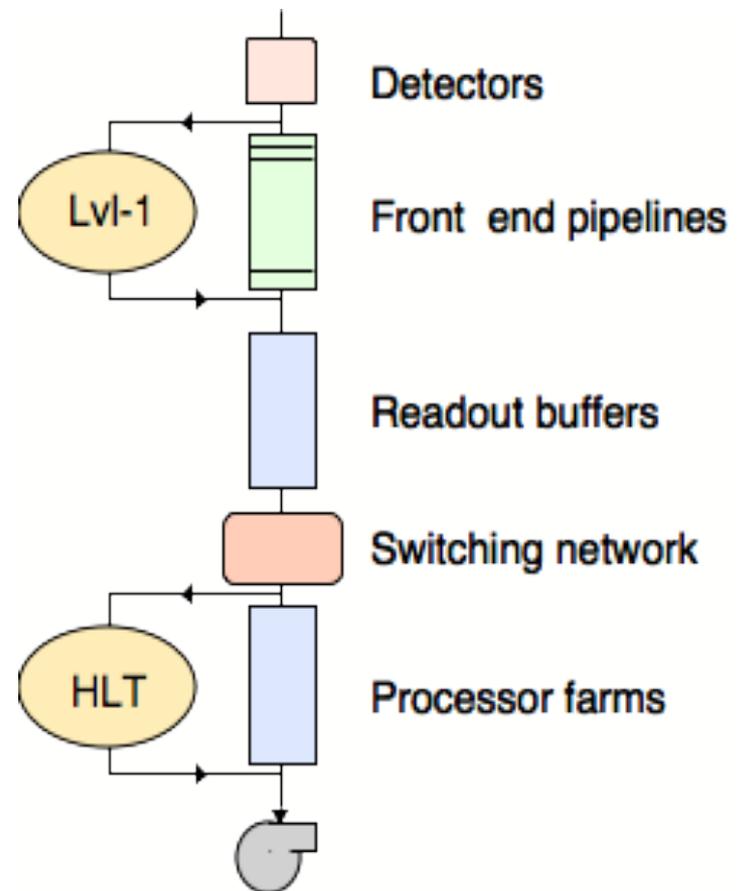
## What do we need?

- Electronic readout of the sensors of the detectors (“front-end electronics”)
- A system to collect the selected data (“DAQ”)
- A system to keep all those things in sync (“clock”)
- A trigger – multi-level due to complexity



# What I need: Level-1 trigger

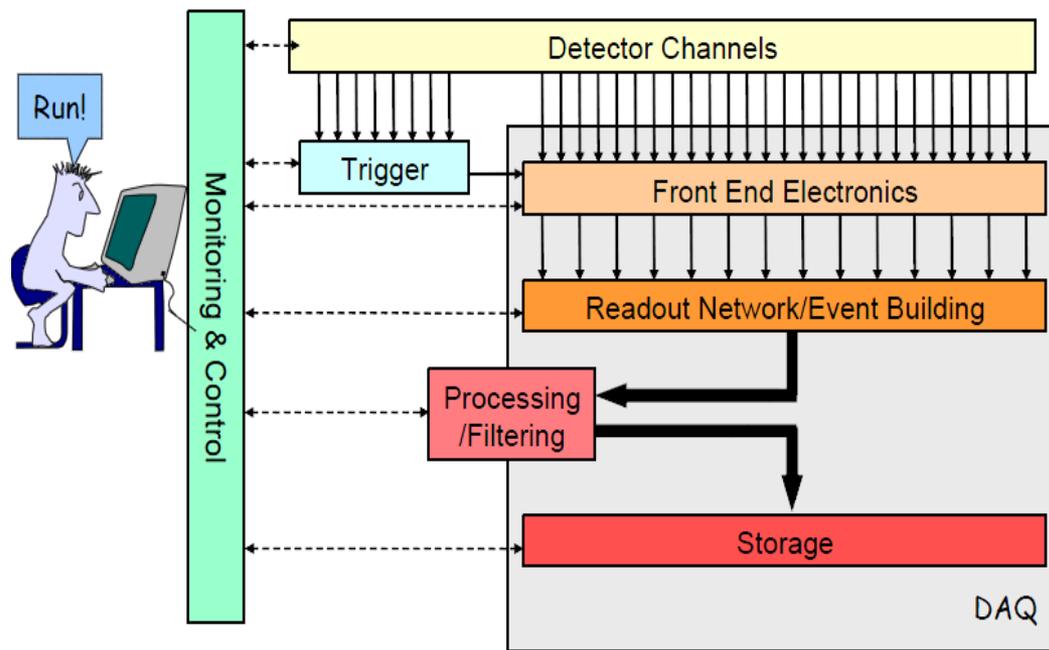
- No (affordable) DAQ system could read out  $O(10^7-10^8)$  channels at 40 MHz  $\rightarrow$  400 TBit/s to read out!
- What's worse: most of these millions of events per second are totally uninteresting
  - Only keep one out of several hundred collisions
- A filter or **first level trigger (L1)** must reject extremely fast the least interesting collisions and retain the more interesting ones for further analysis
- More time available to reject/accept events in the HLT



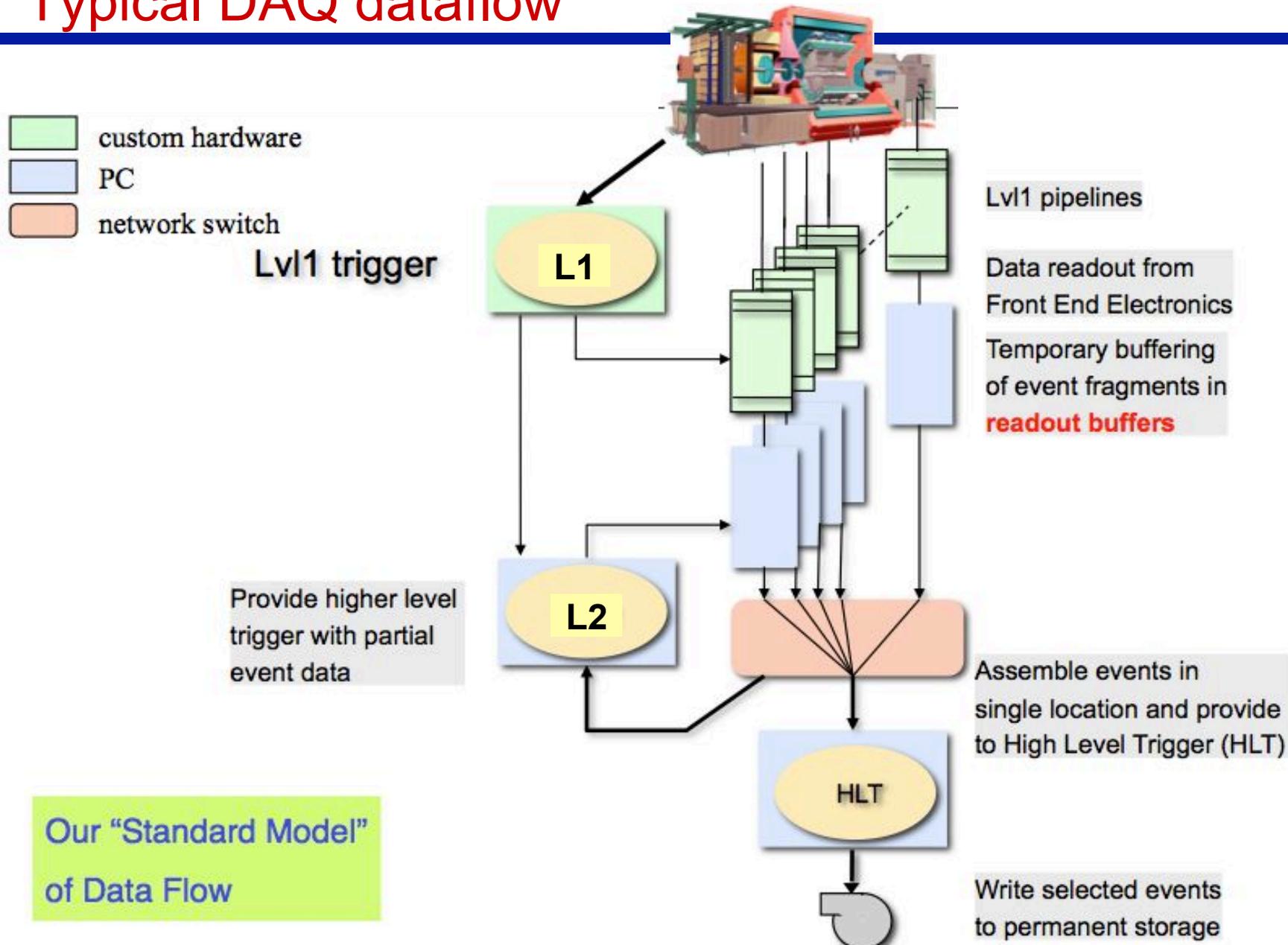
# Let's build a Trigger and DAQ for this

## What do we need?

- Electronic readout of the sensors of the detectors (“front-end electronics”)
- A system to collect the selected data (“DAQ”)
- A system to keep all those things in sync (“clock”)
- A trigger – multi-level due to complexity
- A Control System to configure, control and monitor the entire DAQ



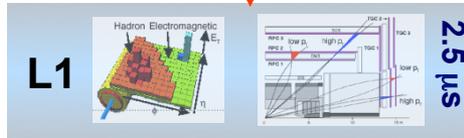
# Typical DAQ dataflow





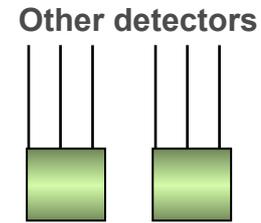
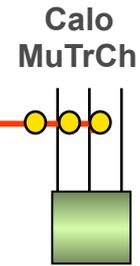
# ATLAS Architecture: L1 Trigger

## Trigger



20 MHz

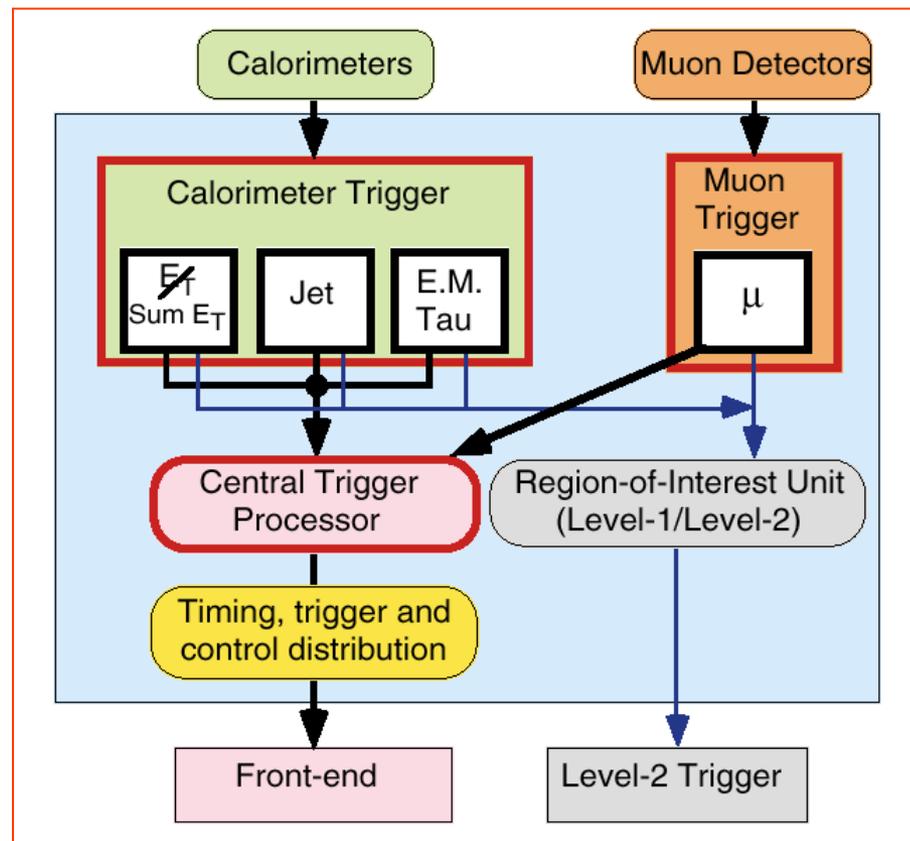
## DAQ



FE Pipelines

# L1 Trigger

- Calorimeter and muons only
- Simple algorithms on reduced data granularity
- Hardware trigger in
  - FPGA (Field-programmable gate array) and ASIC (Application Specific Integrated Circuit)
  - Programmable thresholds
  - Selection based on particle type, multiplicities and thresholds
- Reject the bulk of uninteresting collisions
- Trigger latency:  $2.5 \mu\text{s}$



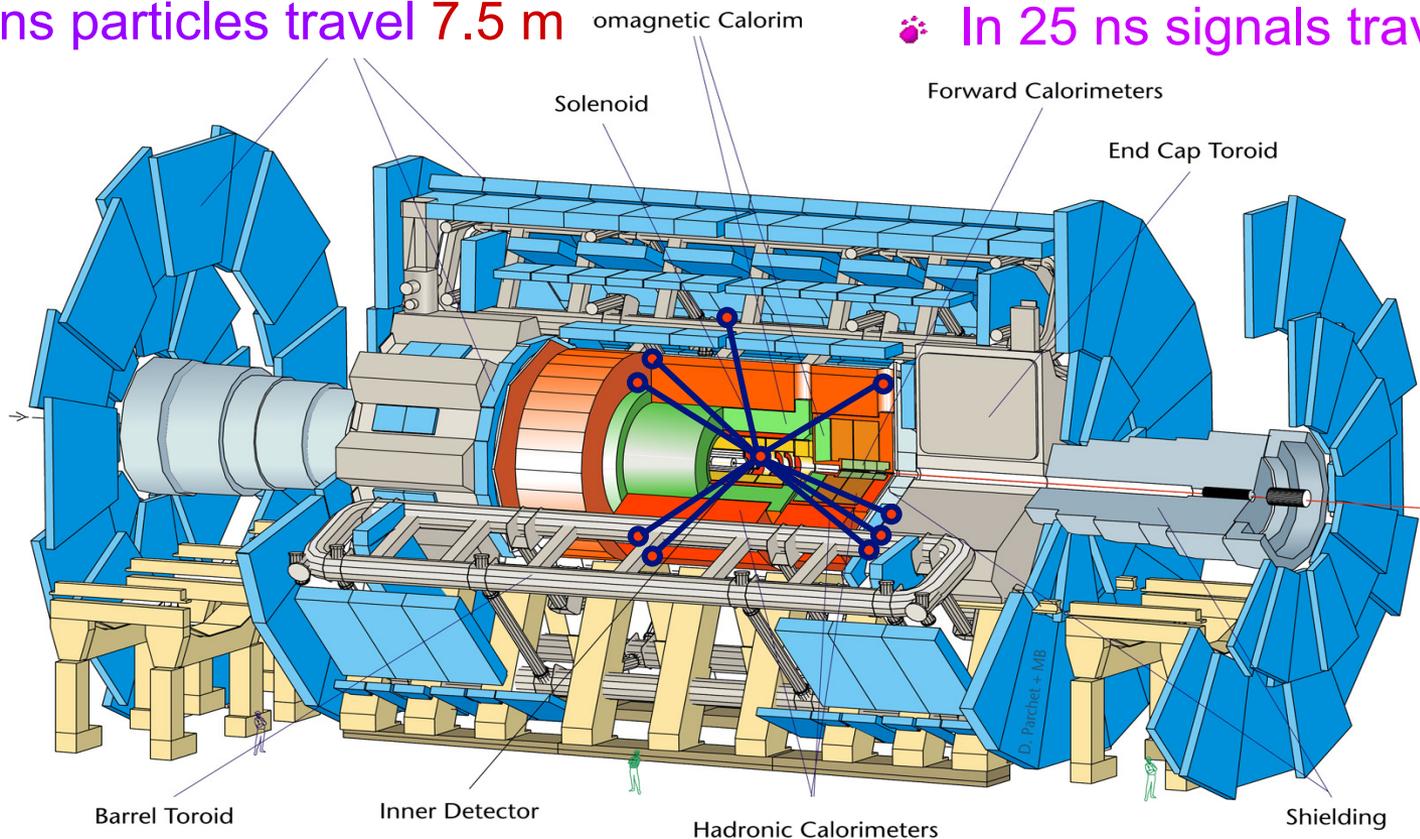
# Level-1 trigger latency

Interactions every 25 ns ...

In 25 ns particles travel 7.5 m

Cable length ~100 meters ...

In 25 ns signals travel 5 m

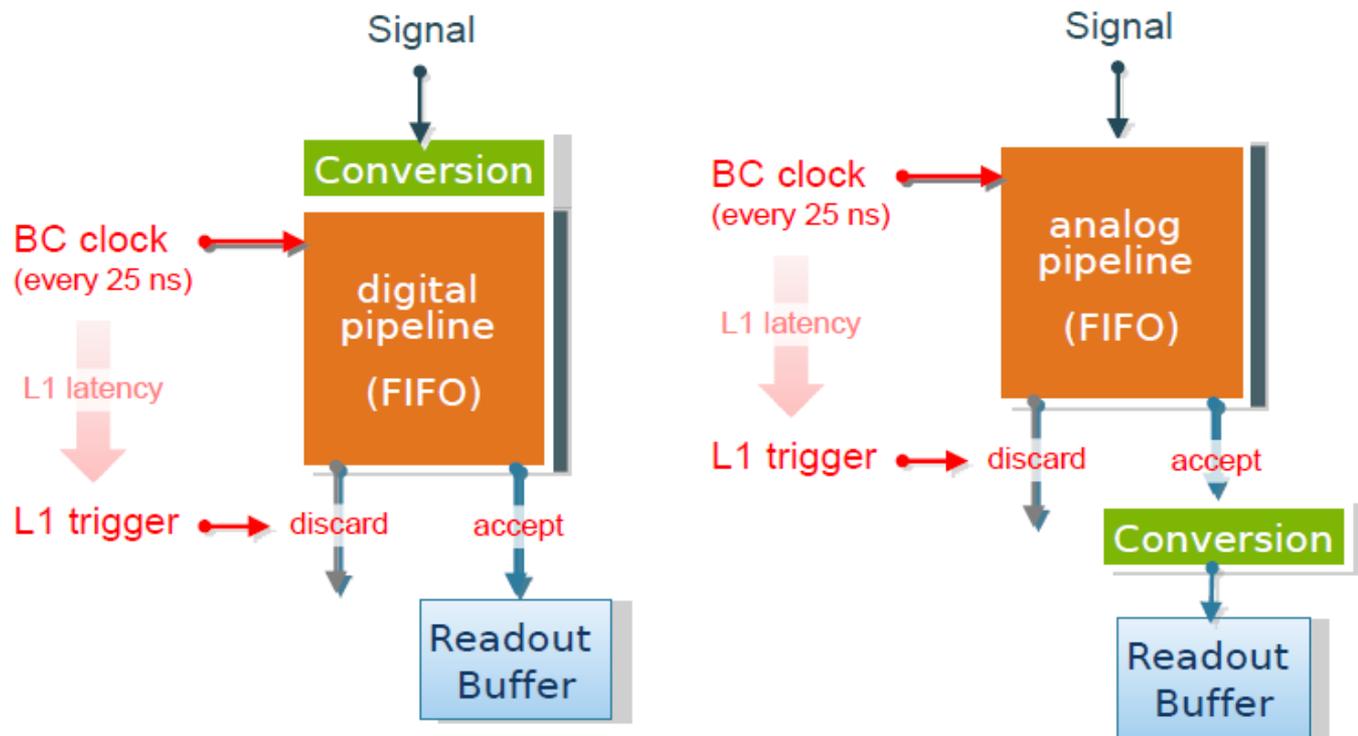


Total L1 trigger latency = (TOF+ cables+processing+distribution) = 2.5  $\mu$ s

For 2.5  $\mu$ s, all signals must be stored in electronics pipelines

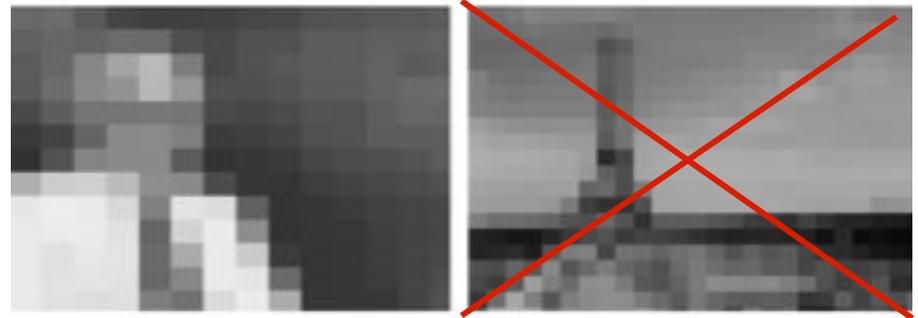
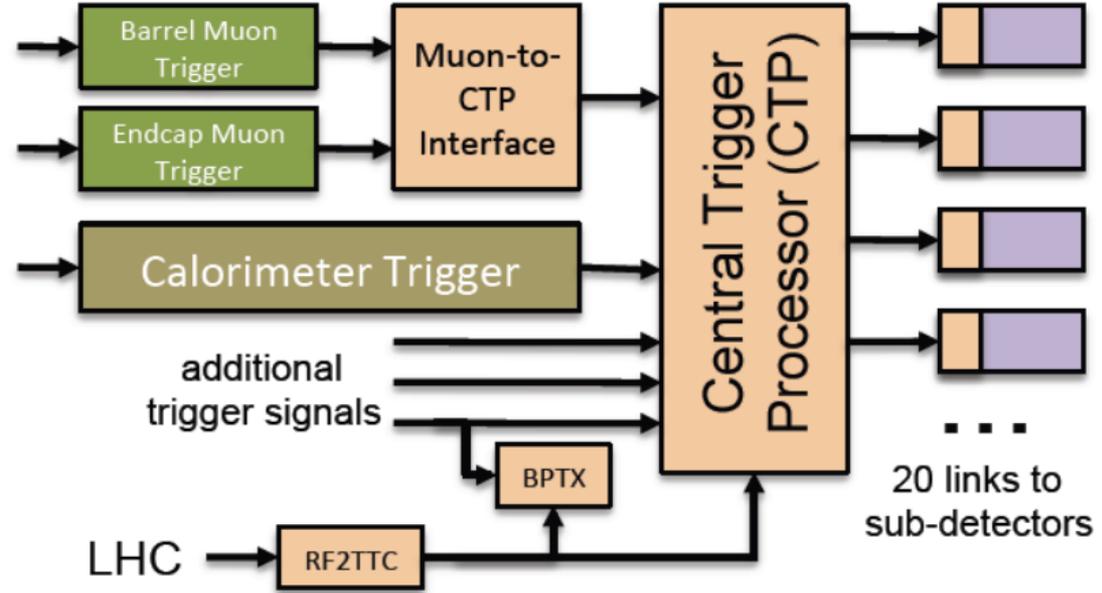
# While L1 is doing its job...

- During L1 processing data for all bunch crossings buffered
- Use pipeline in data path for holding data
  - many variations (analog/digital, on/off detector)
- Use pipelined front-ends
- Length of pipeline determines maximum L1 latency



# ATLAS Central Trigger Processor (CTP)

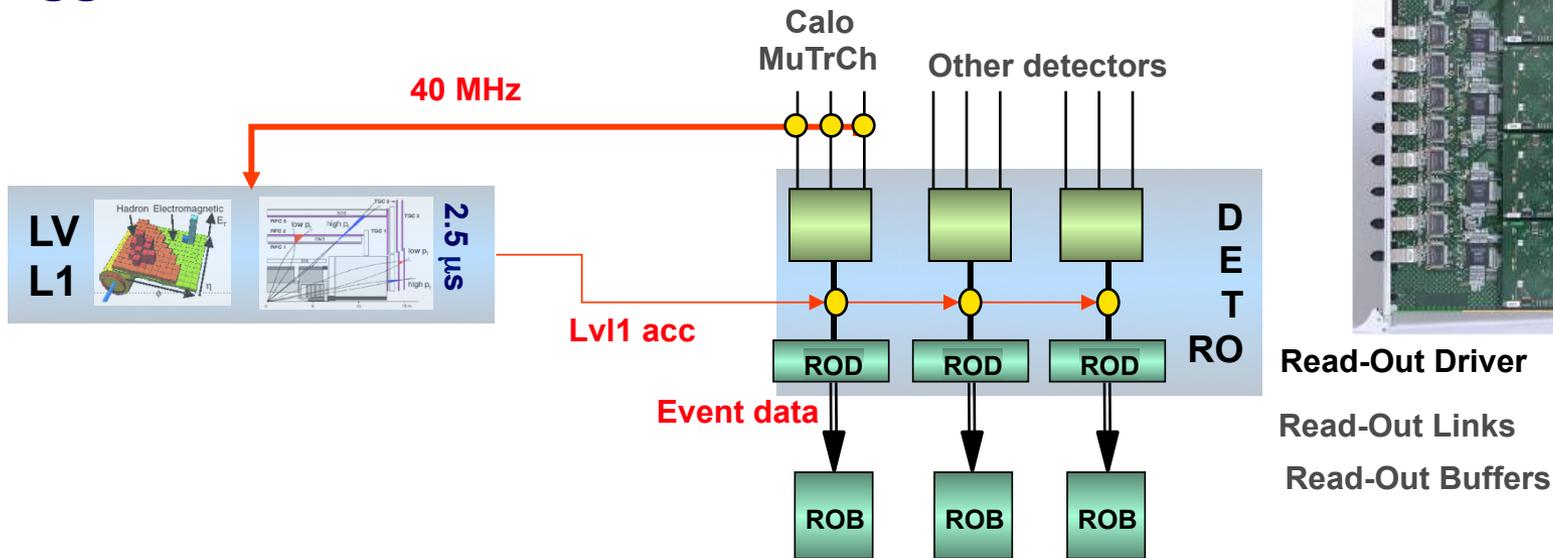
- It's here where all information from the muon and calorimeter triggers are collected (via a bus)
- Can combine info e.g. e+jet, decide if you want to keep your event
  - Can also do **prescaling** e.g. accept only 1 out of 100 events of given type
  - Only keep one out of several hundred collisions
- If something interesting was found it generates the Level-1 Accept (L1A)
  - The L1A is distributed via the TTC system to the detector front-ends



# ATLAS Architecture: Readout Buffer

## Trigger

## DAQ



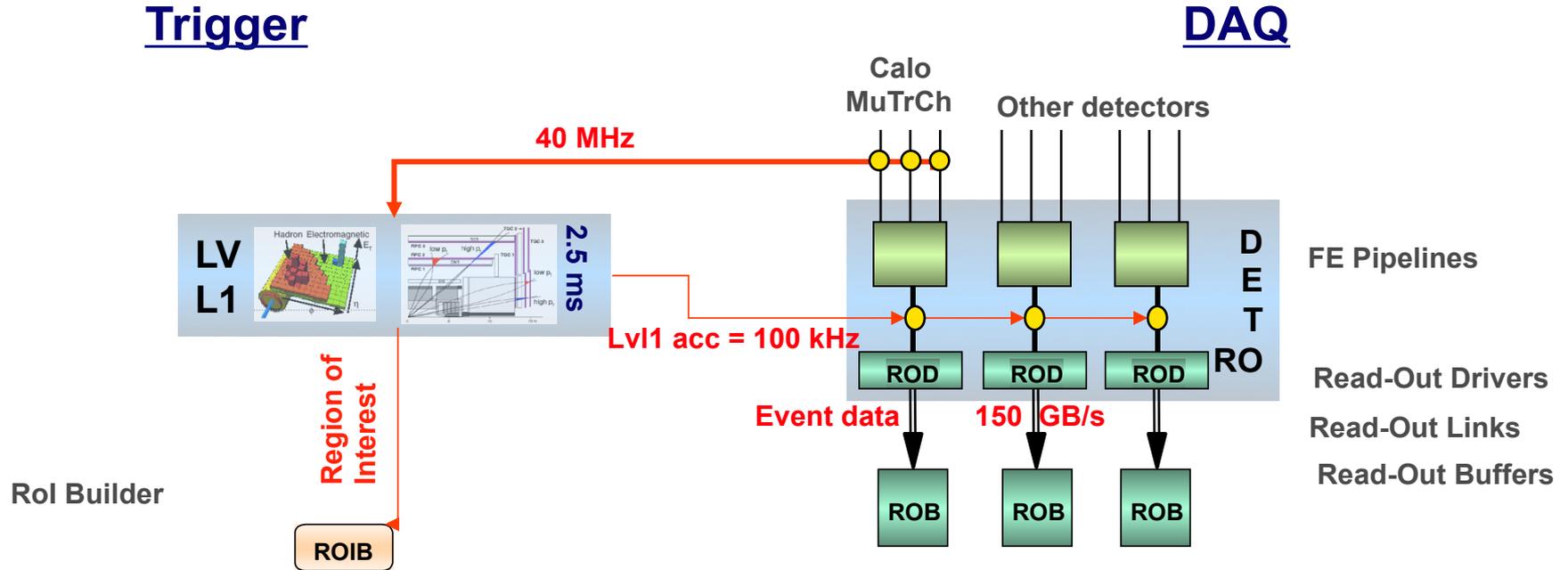
Read-Out Driver

Read-Out Links

Read-Out Buffers

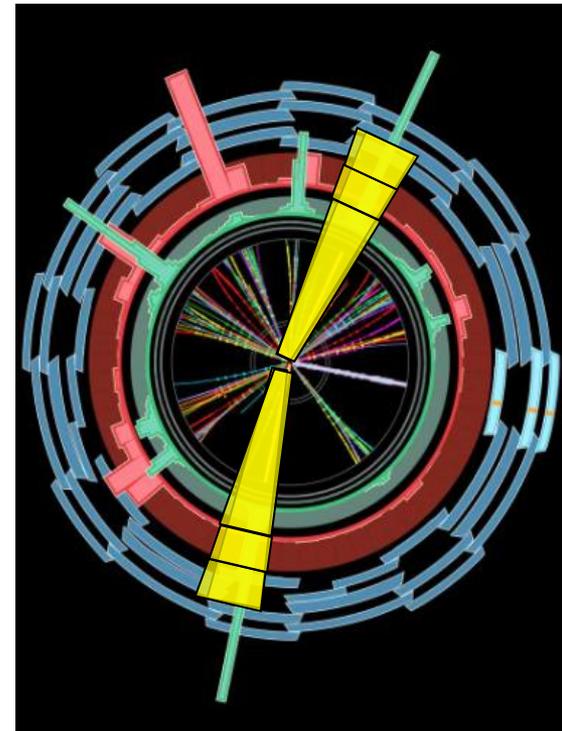
- Upon L1A signal, detector front-ends start sending data of the accepted event to the detector ROD's (Read-Out Drivers)
- Detector ROD's receive data, process and reformat it (as needed) and send it via fibre links (Read-out Links (ROL)) to Read-out system (ROS)
- Holds data up to L2 accept/reject

# ATLAS Architecture: Region of Interest Builder



# Region of Interest (RoI)

- L1 result contains the  $(\eta, \phi)$  coordinates of regions containing high- $p_T$  L1 trigger objects
- There is a **simple** correspondence  $\eta-\phi$  region  $\leftrightarrow$  ROB number(s) (data fragments containing a certain number of readout units)
  - Identify for each RoI the list of ROBs with the corresponding data from each detector (quick procedure)
- RoIB are VME boards with FPGAs L2 (on average) has to process only 1-4% of the data volume; save on
  - Processing time
  - Bandwidth
- Note: RoI approach only used by ATLAS at LHC



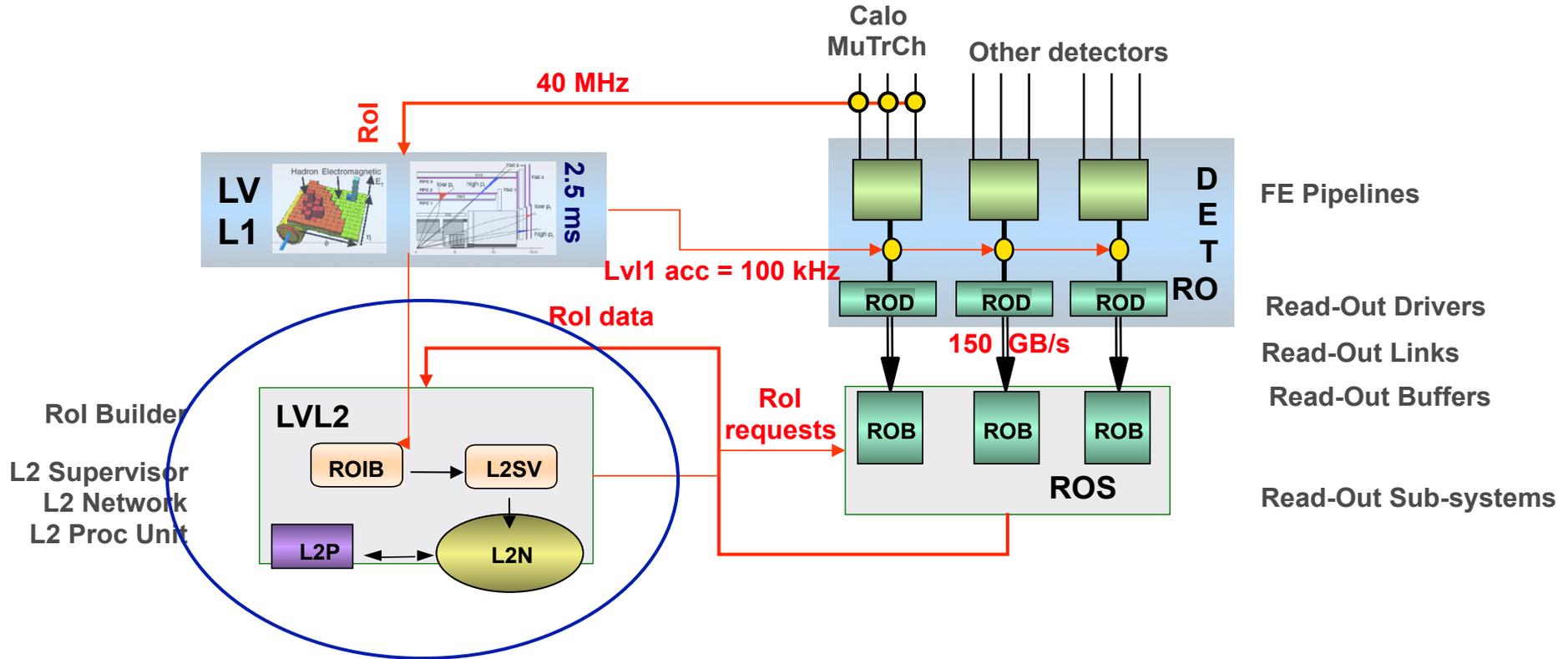
Examples for RoI-based triggers:

- Muons
- Electrons/Photons
- Jets
- Taus

# ATLAS Architecture: Level-2 Trigger

## Trigger

## DAQ



# L2 Trigger

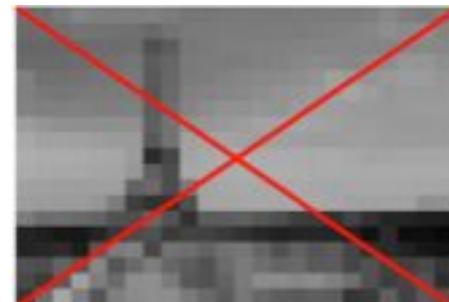
- Software trigger running on a farm of PCs

- Aim

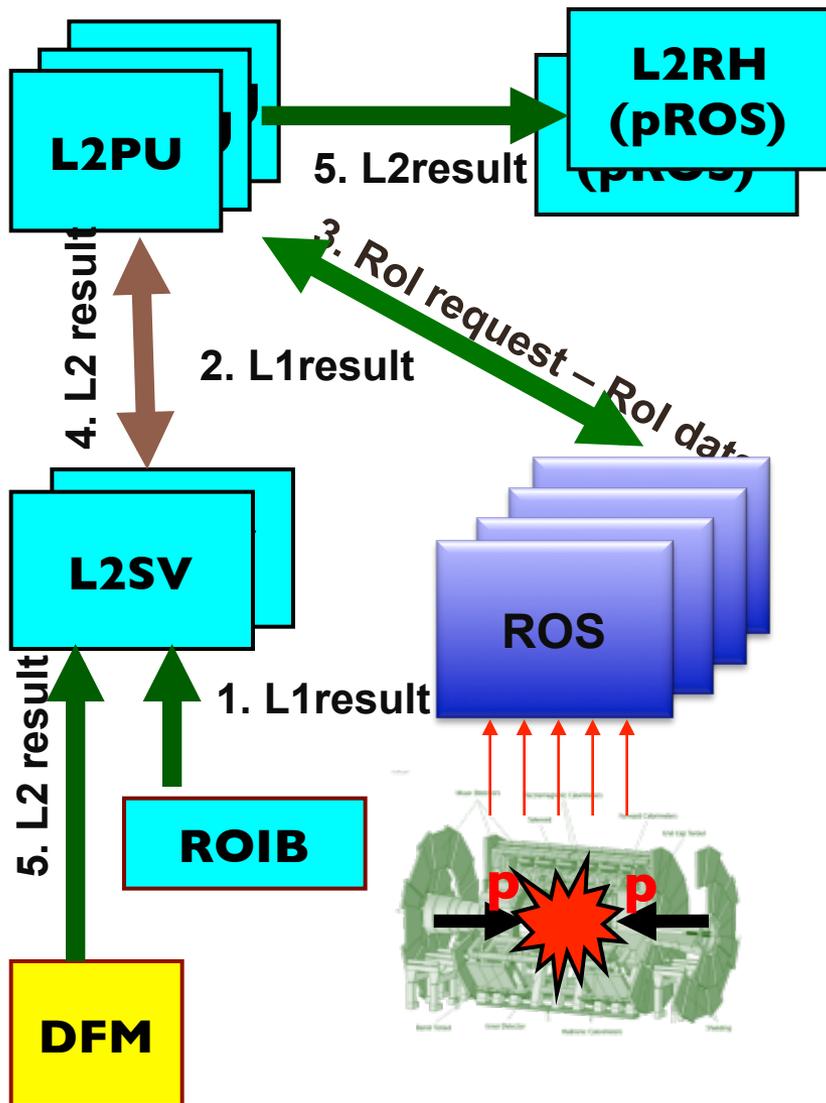
- overall time budget in L2 : 75 ms average
- rejection factor : x 30

- Processing scheme

- Full readout granularity available
- Fast selection algorithms depending on input object
- Identify objects using “simple” criteria
- Can combine info e.g. e+jet, decide if you want to keep your event



# L2 Trigger

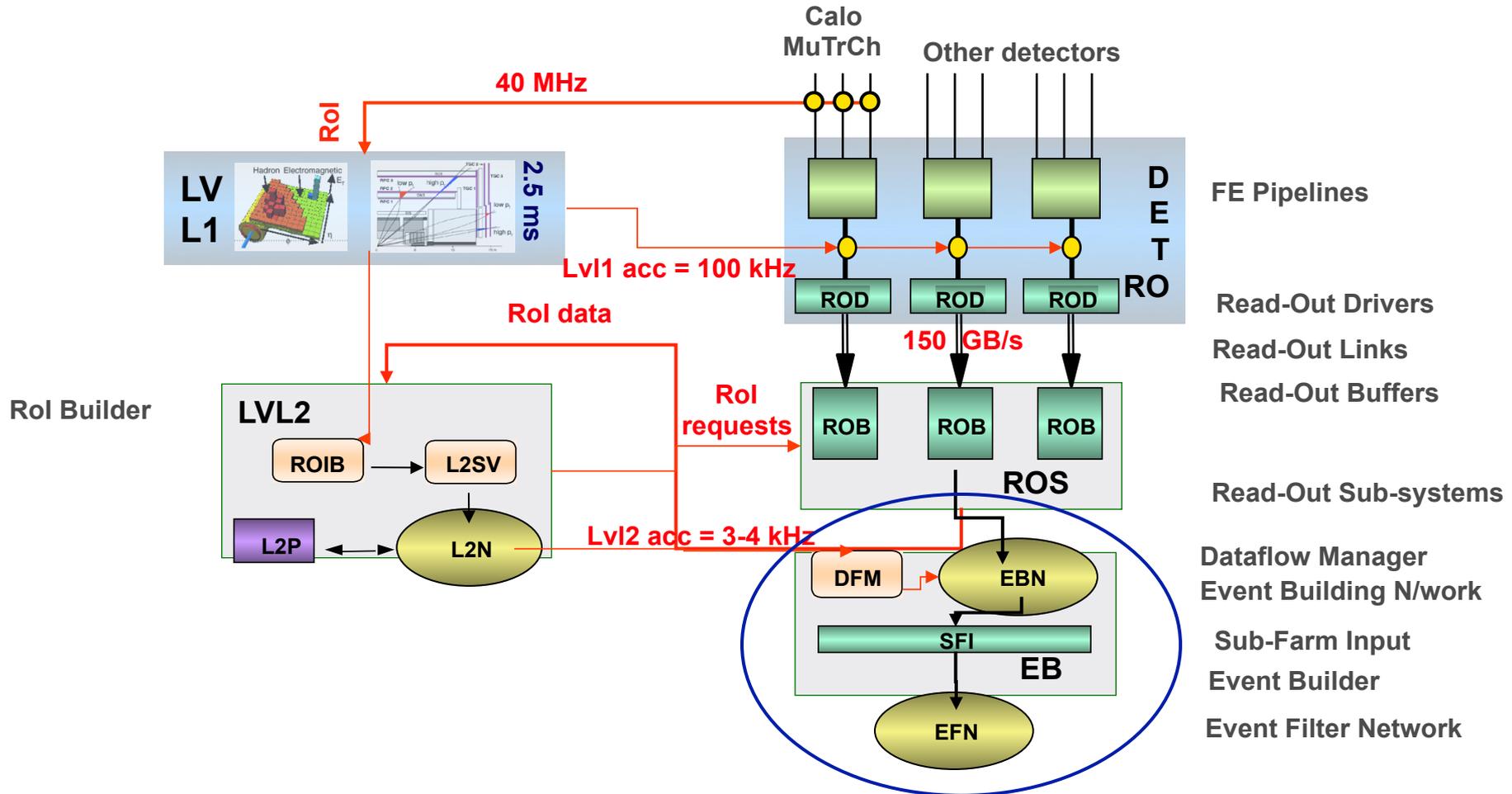


- 1) **Region of Interest Builder (RoIB)** passes formatted information to one of the **L2 supervisors (L2SV)**.
- 2) L2 supervisor selects one of the processors in the L2 farm to process RoI
- 3) **L2 processor (L2PU)** requests data from the ROSs
- 4) L2PU runs selections, produces an accept or reject and informs the L2 supervisor.
- 5) For an accept result is stored in **L2 ResultHandler (L2RH)**
- 6) L2 supervisor passes decision to the **DataFlow Manager** (controls Event Building).

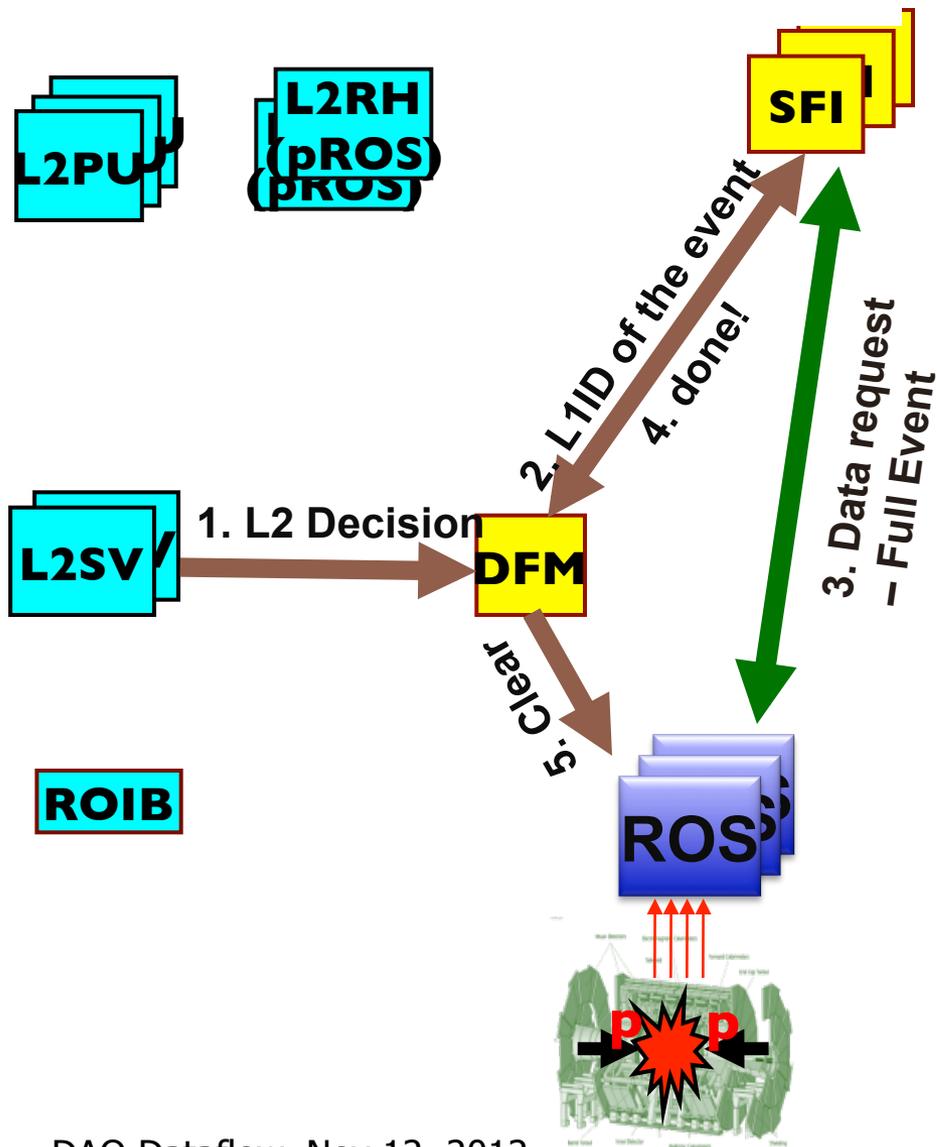
# ATLAS Architecture: Event Builder

## Trigger

## DAQ



# Event Builder

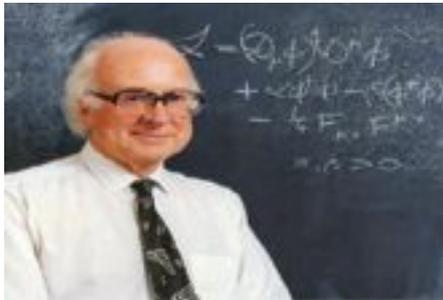


- 1) L2 Supervisor informs **DataFlow Manager (DFM)** of event accepted by L2
  - 2) DFM selects a **Sub-Farm Input (SFI)** and sends to SFI the request to build the complete Event
  - 3) SFI requests **ROS**'s to send event data (L2 pulls event)
  - 4) When done SFI informs DFM.
  - 5) For rejected events and for events for which event Building has completed DFM sends "clears" to the ROSs (for 100 - 300 events together).
- Network traffic for Event Building is ~5 GB/s



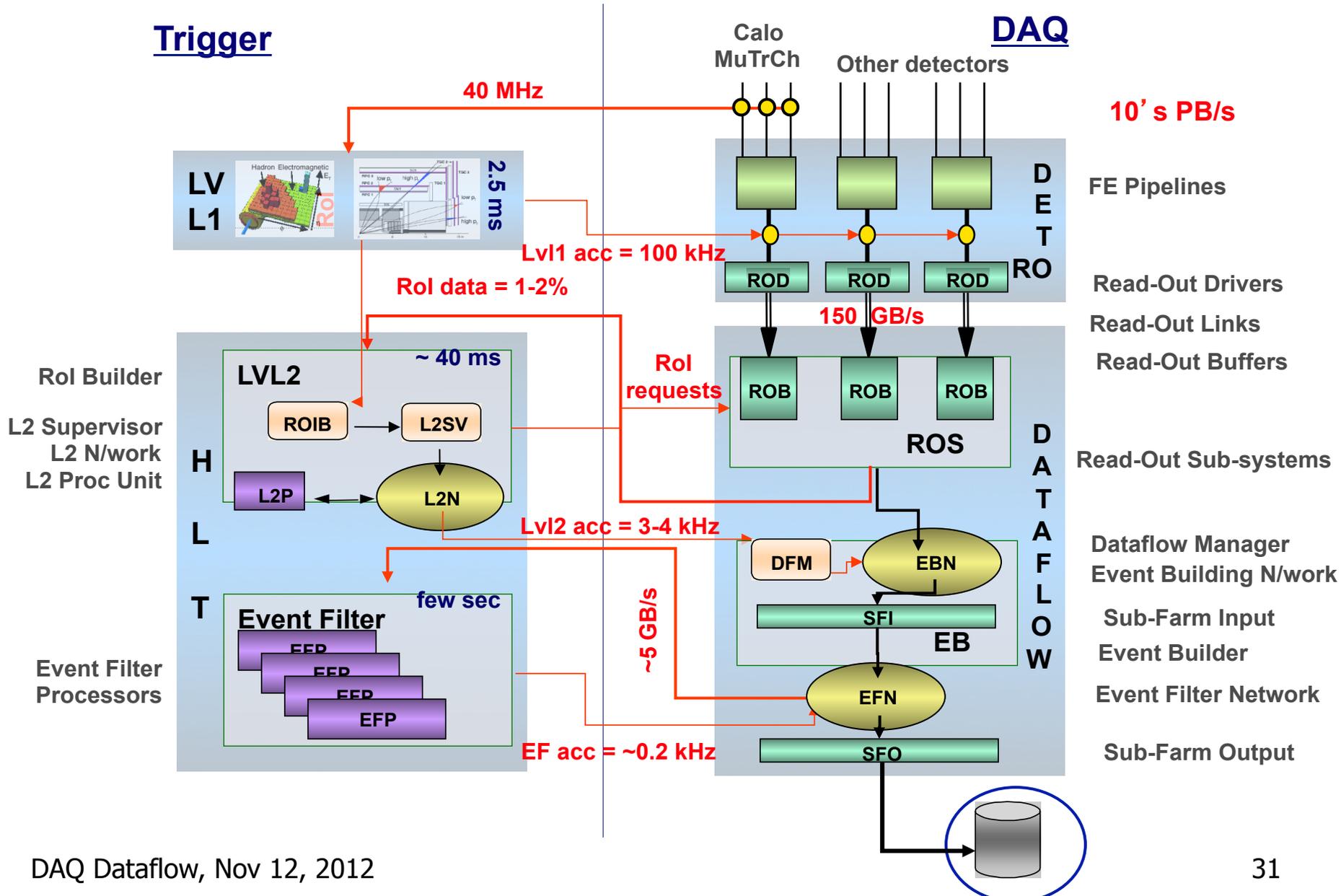
# Event Filter

- Final selection in software triggers using large commercial PC farms
  - Latency  $\sim 4s$
  - access to full granularity and offline like reconstruction algorithms, improved ability to reject events



- Note, there is a flexible boundary between L2 and EF farm

# ATLAS Architecture: Storage



# Data Logger



- Sub-farm output (SFO)
  - Receive events and write them into files on local disks
  - Dedicated nodes with high performance RAID disks
- Events are sorted out to different files according to their “Physics Stream” content (e.g. “Muons”, “Jets”, “EGamma”, etc.):
  - Events belonging to multiple streams will end up in multiple files
- Files are closed when they reach 2 GB or at end of a luminosity block
  - To assist with overall normalisation each data-taking run is subdivided into periods of a ~ minute called a luminosity block. During each block the beam luminosity should be constant and can also exclude any blocks where there is a known problem)
- Closed files are finally transmitted via GbE to the CERN offline reconstruction farm, subsequently erase from local SFO disk

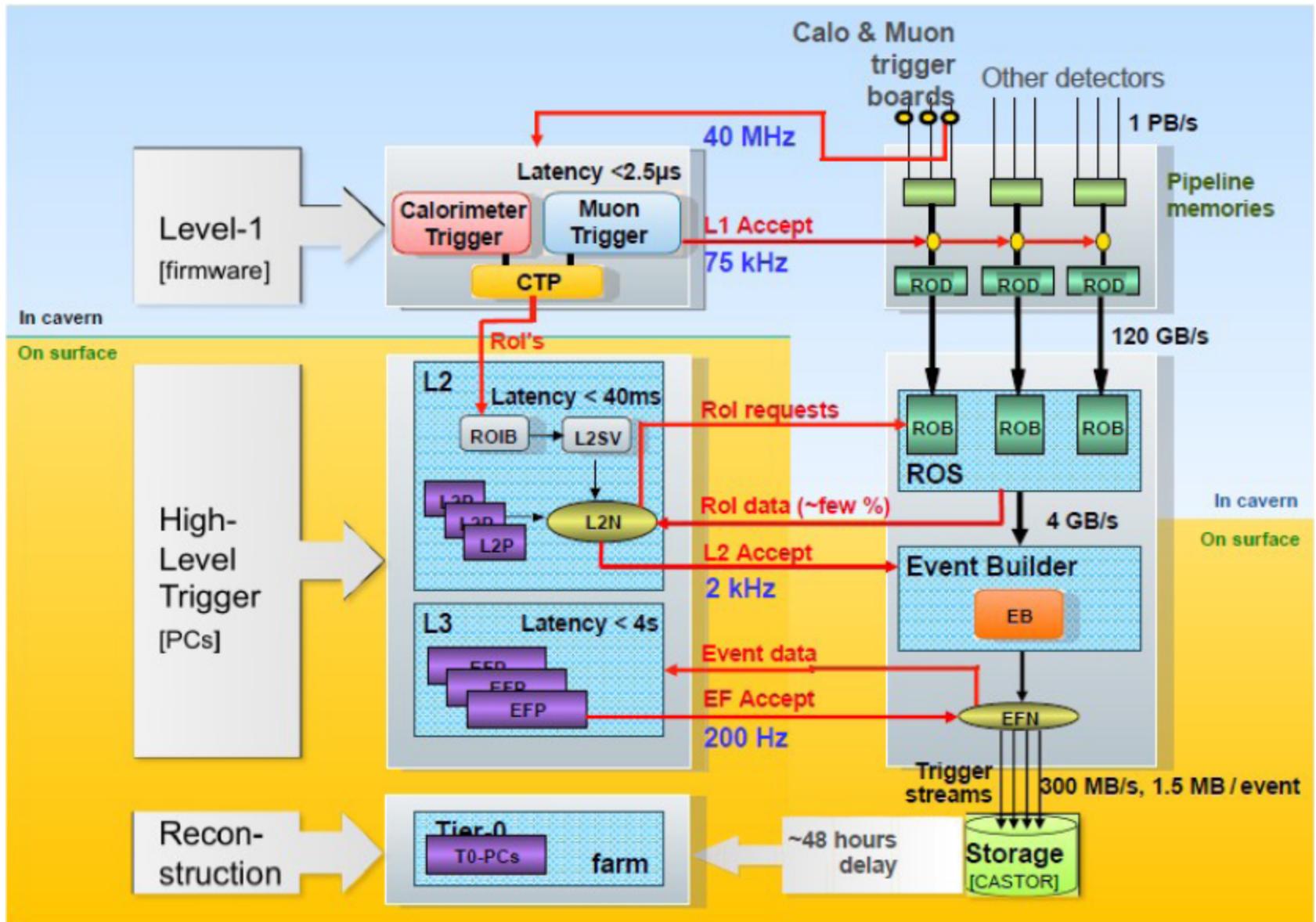
# Summary

- Challenge to design efficient trigger/DAQ for LHC
  - Very large collision rates (up to 40 MHz)
  - Very large data volumes (tens of MBytes per collision)
  - Very large rejection factors needed ( $>10^5$ )
- Used ATLAS event DataFlow as an example of a large TDAQ system
  - L1 trigger – ReadOut System – L2 trigger – Event Builder – EF – data logger
  - Showed the complexity of operations to handle the complex system
  - Fear it was at times very technical but hopefully has given you an idea what going on ‘behind the scene’
- We’ll look in detail at the trigger aspects in the next lecture
  - This one will be less technical and more physics-oriented!

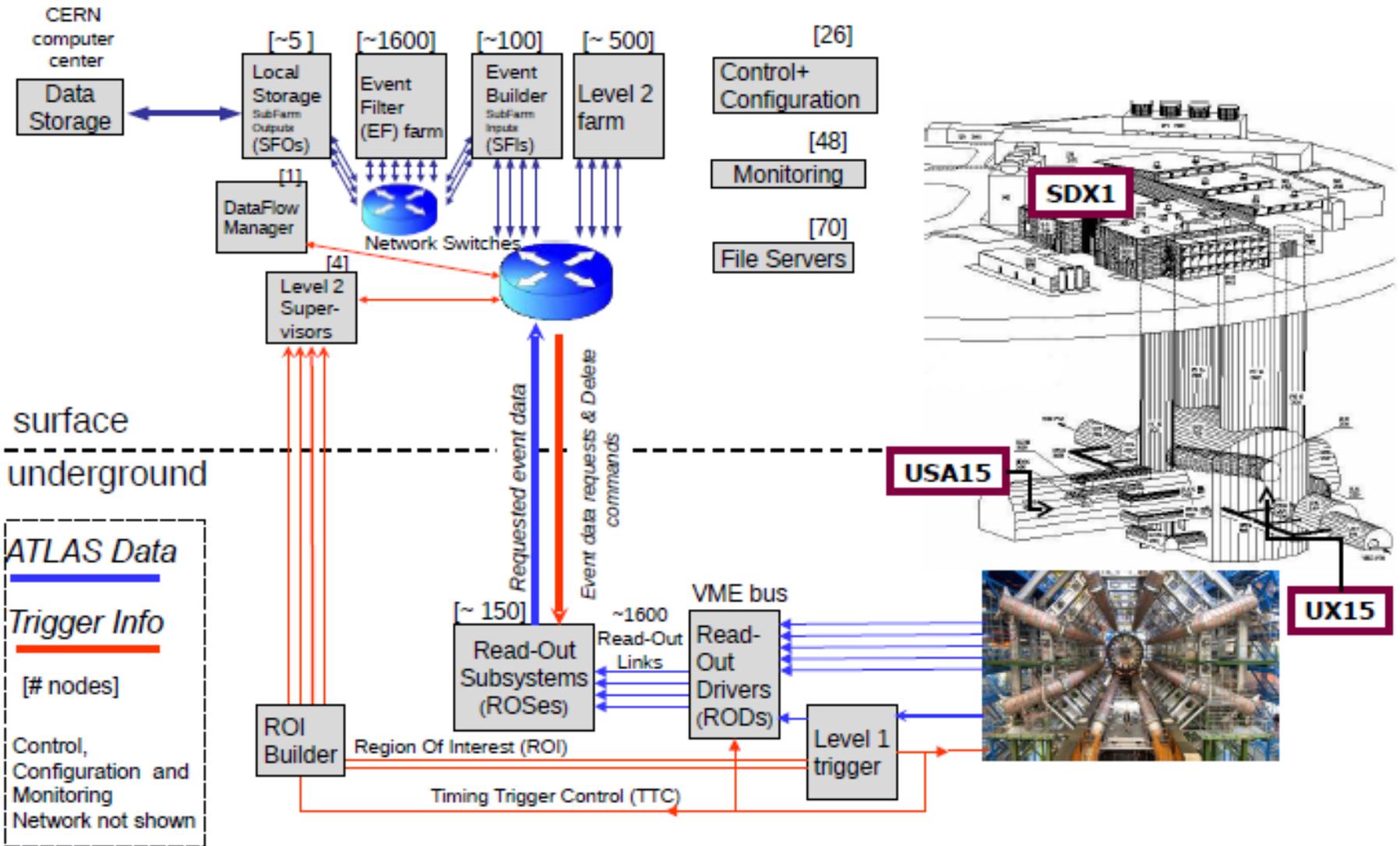
# Backup

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# The ATLAS Trigger/DAQ System



# ATLAS Trigger / DAQ Data Flow

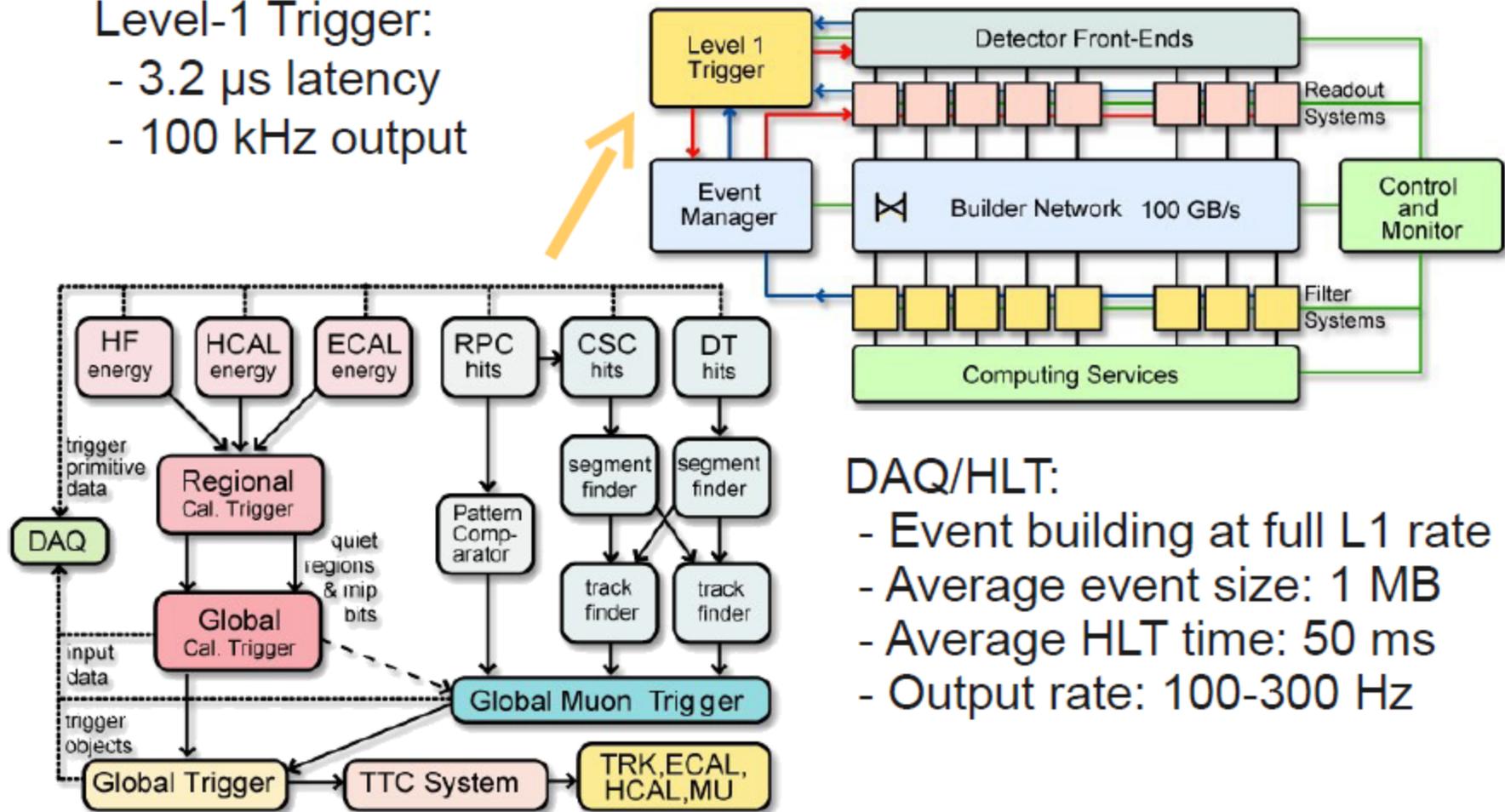


# The CMS Trigger/DAQ System

## Overall Trigger & DAQ Architecture: 2 Levels

### Level-1 Trigger:

- 3.2  $\mu$ s latency
- 100 kHz output

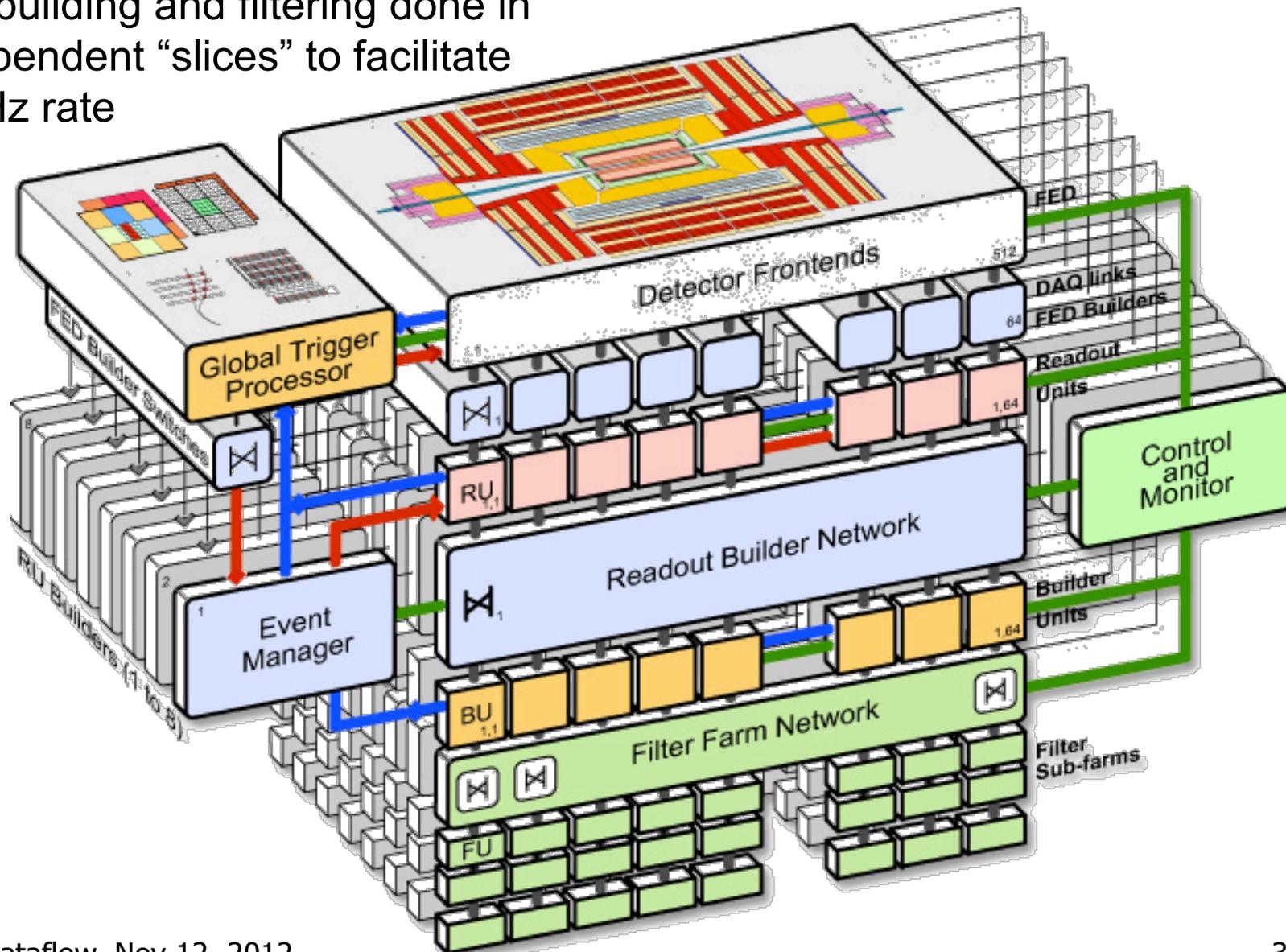


### DAQ/HLT:

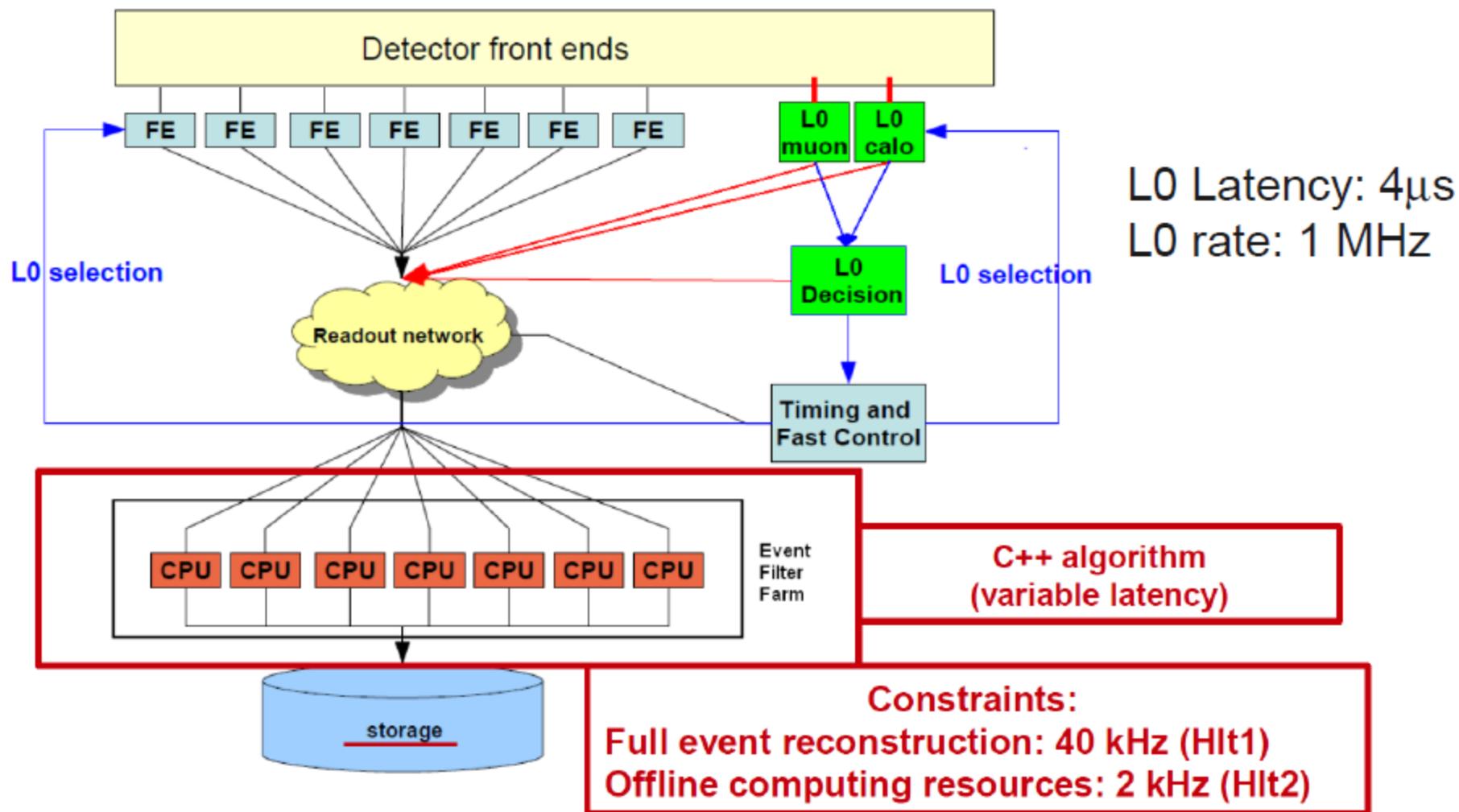
- Event building at full L1 rate
- Average event size: 1 MB
- Average HLT time: 50 ms
- Output rate: 100-300 Hz

# CMS “3D” Event Builder

Event building and filtering done in 8 independent “slices” to facilitate 100 kHz rate



# LHCb DAQ System



# LHC-b Trigger System

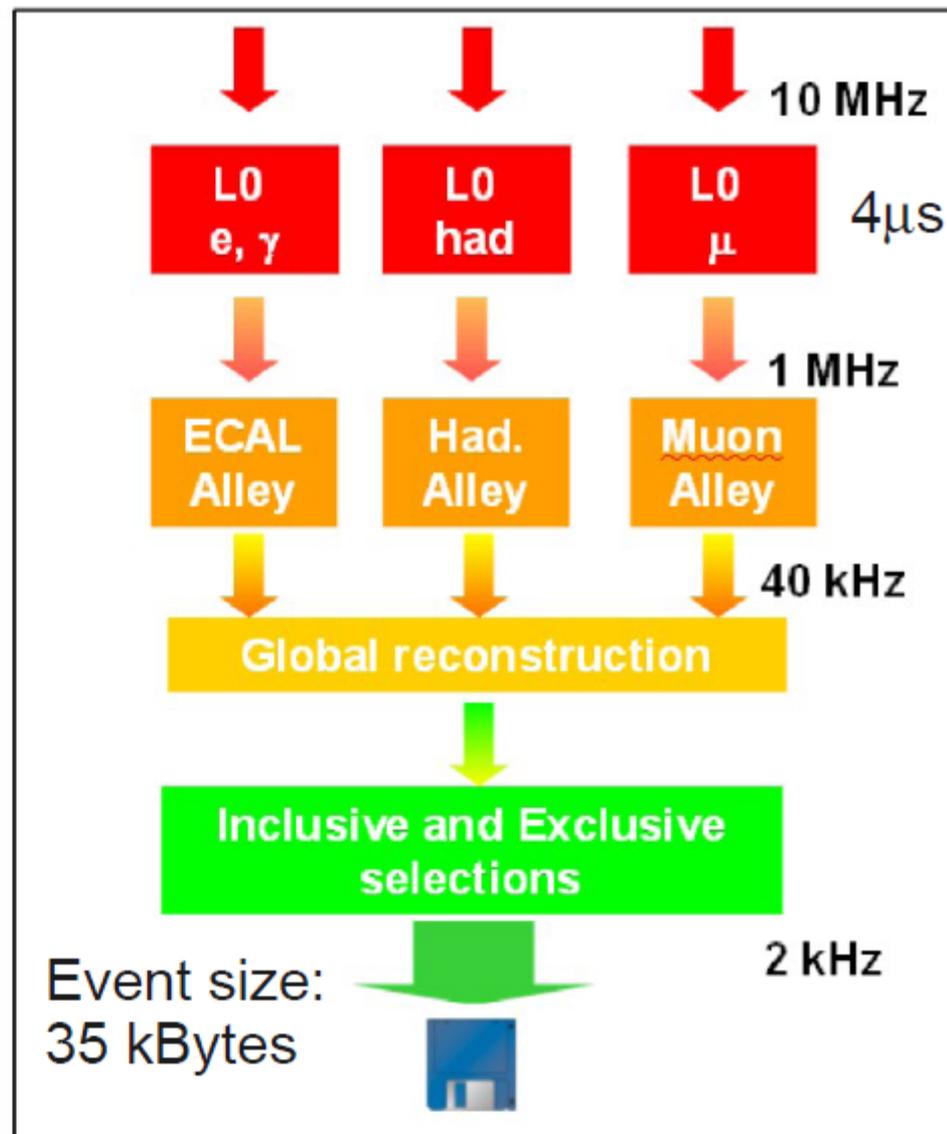
**Level-0 (hardware): High  $E_T$  /  $p_T$  candidates**

**HLT1 (software):**

- Partial Reconstruction on ROIs to confirm L0 candidates
- Use VELO for IP filter
- Add extra tracks

**HLT2 (software):**

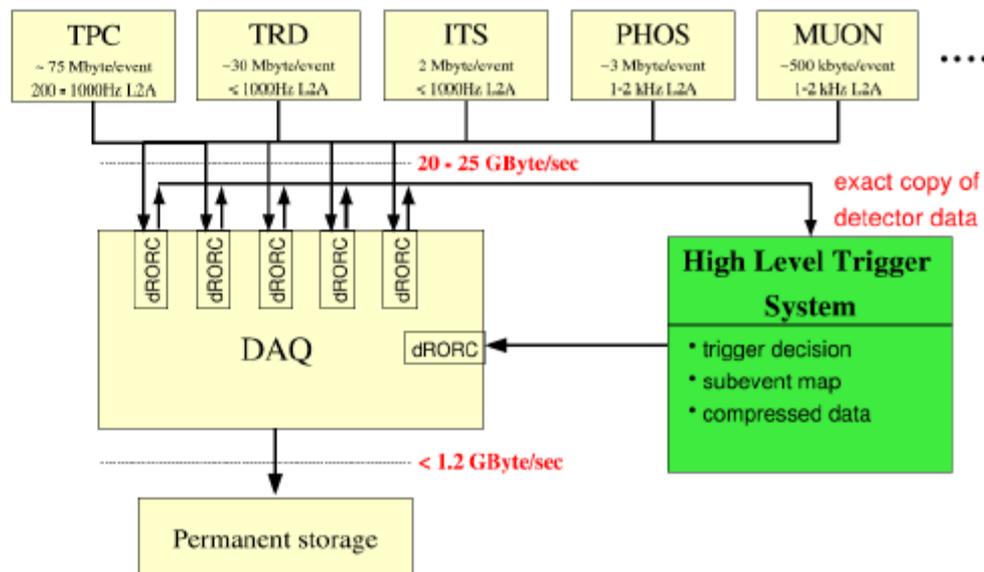
- Full Reconstruction of event
- RICH available for PID
- Few tracks (inclusive)
- All tracks (exclusive)



# ALICE Trigger/DAQ System

ALICE has different constraints:

- Low rate (max 8 kHz of Pb+Pb)
- Very large events (>40 Mbytes)
- Slow detector (TPC ~ 100  $\mu$ s)



## 3 levels of hardware triggers:

### Collision

**L0: Trigger detectors detect collision**  
(V0/T0, PHOS, SPD, TOF, dimuon trigger)

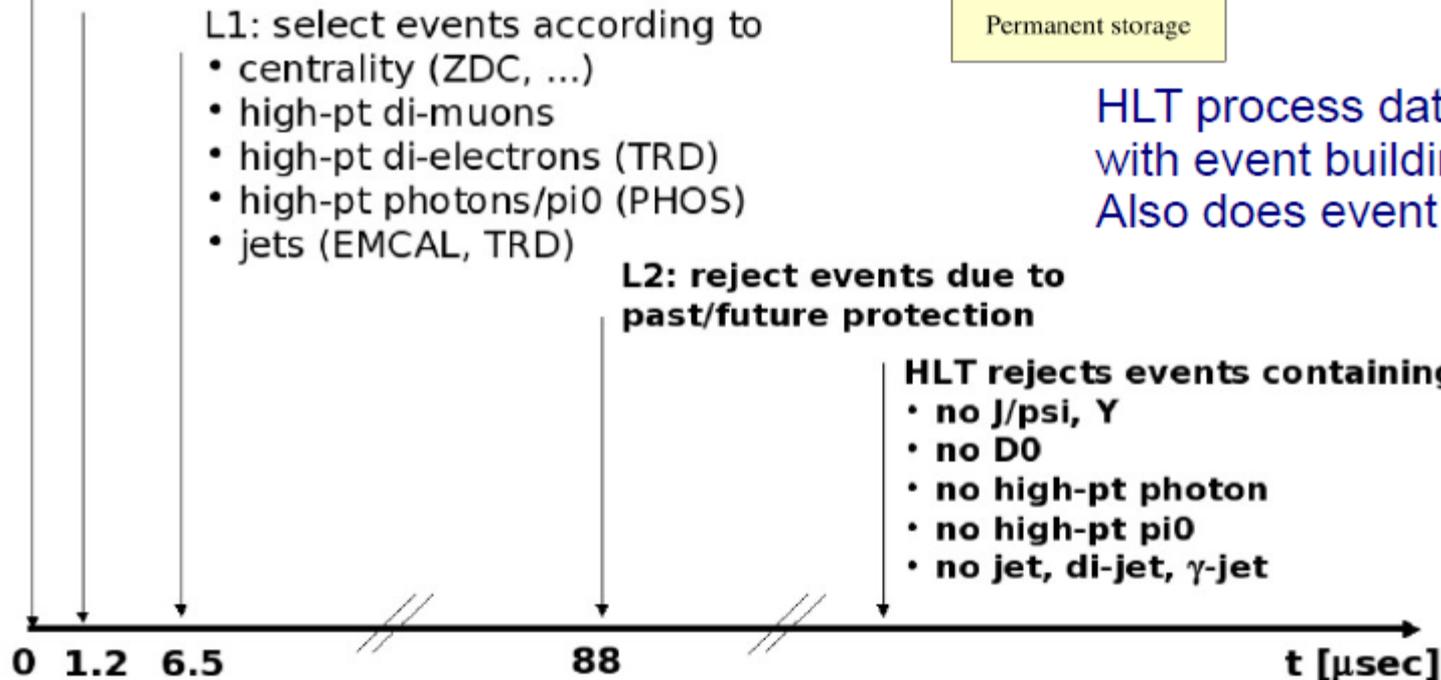
**L1: select events according to**

- centrality (ZDC, ...)
- high-pt di-muons
- high-pt di-electrons (TRD)
- high-pt photons/pi0 (PHOS)
- jets (EMCAL, TRD)

**L2: reject events due to past/future protection**

**HLT rejects events containing**

- no J/psi, Y
- no D0
- no high-pt photon
- no high-pt pi0
- no jet, di-jet,  $\gamma$ -jet



HLT process data in parallel with event building  
Also does event compression

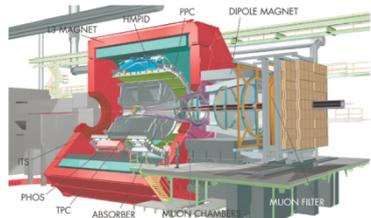
# Trigger/DAQ parameters

**No. Levels**  **Level-0,1,2**  
Trigger Rate (Hz)

**Event**  
Size (Byte)

**Readout**  
Bandw.(GB/s)

**HLT Out**  
MB/s (Event/s)



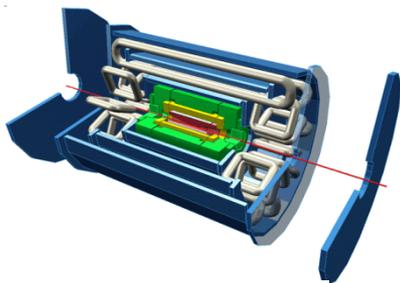
**4**

Pb-Pb **500**  
p-p  **$10^3$**

**$5 \times 10^7$**   
 **$2 \times 10^6$**

**25**

**1250 ( $10^2$ )**  
**200 ( $10^2$ )**



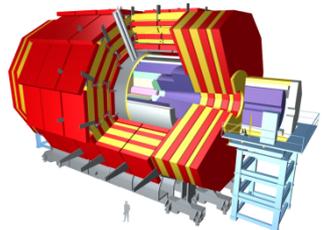
**3**

LV-1  **$10^5$**   
LV-2  **$3 \times 10^3$**

**$1.5 \times 10^6$**

**4.5**

**300 ( $2 \times 10^2$ )**



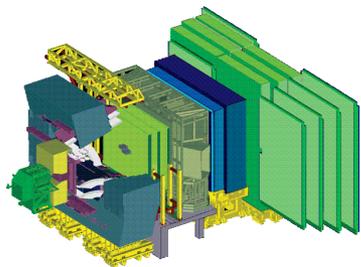
**2**

LV-1  **$10^5$**

**$10^6$**

**100**

**$\sim 1000$  ( $10^2$ )**



**2**

LV-0  **$10^6$**

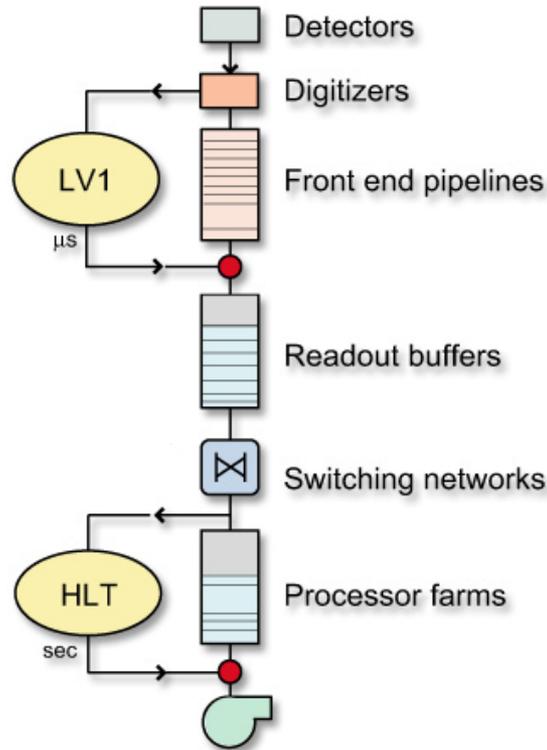
**$3.5 \times 10^4$**

**35**

**70 ( $2 \times 10^3$ )**

# CMS Event Building

**40 MHz**  
Clock driven  
Custom processors



**Level-1 Trigger**  
**Custom design**

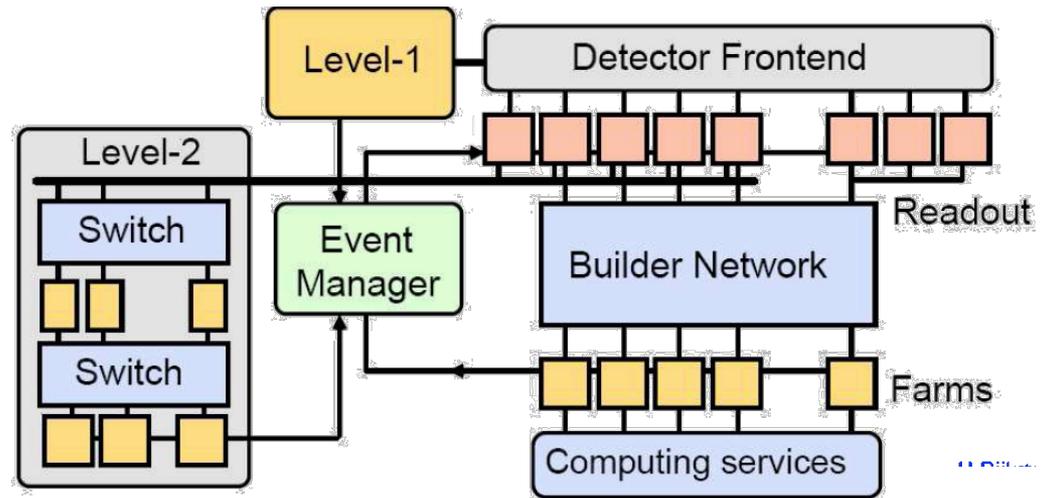
**100 kHz**  
Event driven  
PC network

**High-Level Trigger**  
**Industry products**

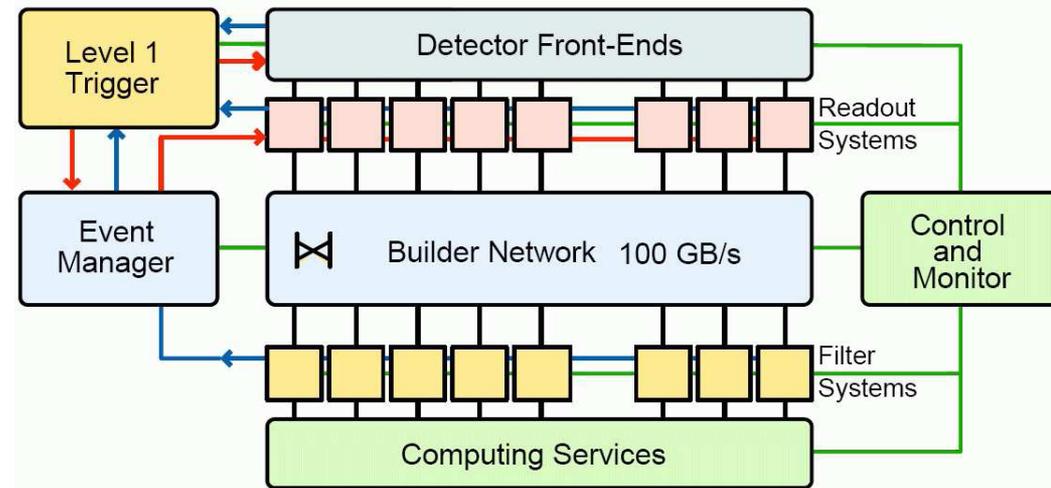
**Level-1 output / HLT input 100 kHz**  
**Network bandwidth 1 Terabit/s**  
**HLT output  $10^2$  Hz**  
**Invest in data transportation and CPU**

# Event Builder

- Send a part first (RoI)
- Run L2 algorithms and decide if you want to keep the event
- If yes, send complete event data



- Alternative (used by CMS, Alice ad LHCb)
  - Send everything, ask questions later
  - Much higher demand on networking



# Lot's of Abbreviations...

- Read-Out Drivers (ROD):
  - subdetector-specific,
  - collect and process data (no event selection)
- Read-Out Link (ROL)
  - 160 MByte/s optical fibre
- Read-Out Buffer input stage (ROBIN) card
  - Part of Readout system
  - 64-bit 66 MHz PCI card - 3 ROL inputs
- Read-Out Subsystem (ROS)
  - Set of PCs
  - Each PC contains 4 ROBINs => 12 ROLs per ROS PC